

Attack on Titan M Vulnerability Research on a Modern Security Chip

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What is Titan M?

- Security chip made by Google, for Pixel devices
- Implements critical security features
 - Keymaster/Strongbox, Weaver, AVB, etc
- Client-server model
- Introduced for:
 - Mitigate side-channel attacks
 - Protect against hardware tampering



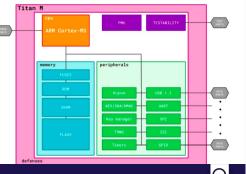
Our previous work in 4 slides

Specification

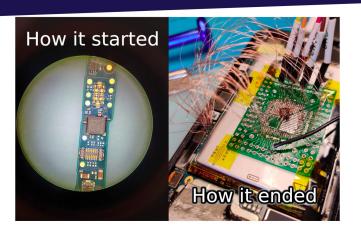


Hardened SoC based on ARM Cortex-M3

- Anti-tampering defenses
- Cryptographic accelerators &
 True Random Number Generator
- UART for logs and console
- SPI to communicate with Android



Hardware Reverse: Finding SPI



Firmware Security Measures



- Secure boot (images are signed and verified at boot)
- No MMU, but MPU to give permissions to the memory partitions
- Only software protection: hardcoded stack canary checked in the SVC handler

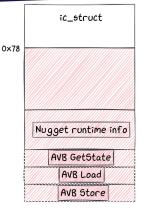
```
if (*CURRENT_TASK->stack != 0xdeadd00d) {
    next = (int)&CURRENT_TASK[-0x411].MPU_RASR_value >> 6;
    log("\n\nStack overflow in %s task!\n",(&TASK_NAMES)[next]);
    software_panic(0xdead6661,next);
}
```



What can we do with the exploit?

Vulnerable buffer placed just before

- runtime data of the chip...
- ... and the list of command handler pointers
- → overwrite command handler addresses to gain code execution!

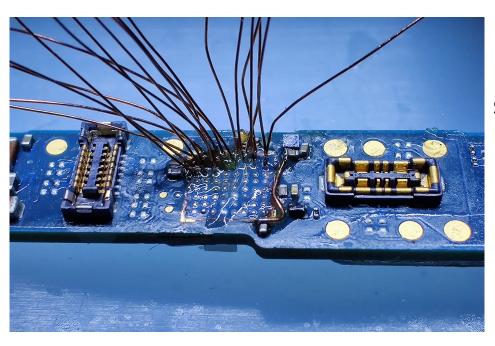


Firmware reverse Interact with the chip Find vulns execution





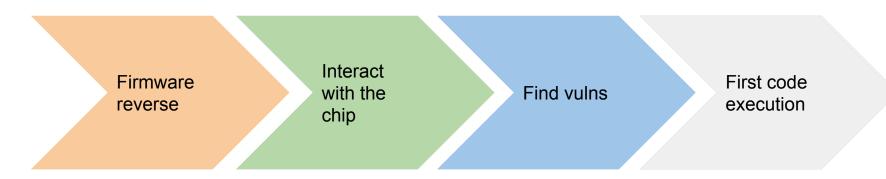
Implemented some tools to interact with the chip



Sniff and send custom commands

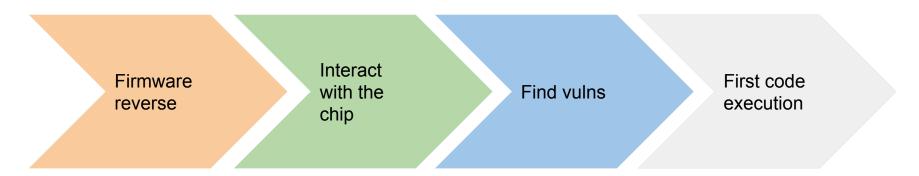
- From Android using Frida and our tool nosclient
- On this hardware level thanks to
 @doegox's magic hands

Several vulnerabilities reported, including a downgrade issue



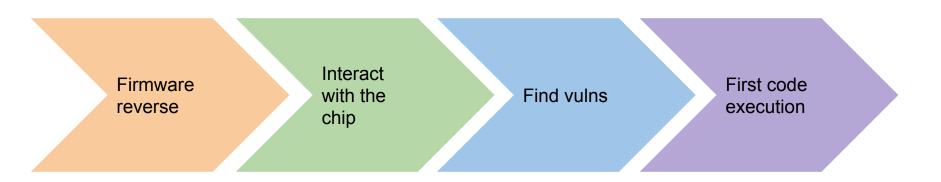
Published the first code execution on this target

Several vulnerabilities reported, including a downgrade issue



- CVE-2021-0939: A memory leak allowing to reveal parts of the Boot ROM
- CVE-2021-1043: A downgrade issue allowing to flash any firmware
 - → With a side effect: all the secrets are erased

Leak various hidden parts of the firmware



Including the Boot ROM

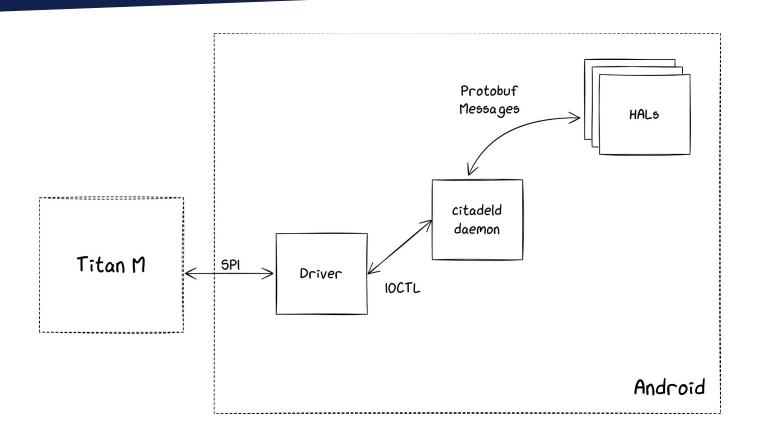
TL;DR: what we learned

- Security chip based on ARM Cortex-M3
- Closed source but based on EC
 - An open source OS made by Google
 - Written in C and conceptually simple
 - No dynamic allocation
- Most of the code is divided into tasks
- SPI bus used to communicate with Android
- UART bus used for logs and minimalistic console

EC Tasks

idle → system events, timers hook → system control task nugget AVB → secure boot management faceauth → biometric data identity → identity documents support keymaster → key generation and cryptographic operations → storage of secret tokens weaver console → debug terminal and logs

Communication with the chip



Firmware security

- No dynamic allocation → no UaF and similar
- Secure boot (images are signed and verified at boot)
- MPU to give permissions to the memory partitions
 - Custom interface to set the eXecute permission
 - No WX permissions by default
- Only software protection: hardcoded stack canary

What we show today

- Fuzzing is useful also against Titan M
 - Even on such contrainted target, we can get interesting results
- Two approaches
 - Black-box fuzzer vs emulation-based fuzzer
- Exploiting without debuggers or stack traces
- How a single **software** vulnerability can lead to
 - Code execution
 - Compromise of the security properties guaranteed by the chip

Blackbox fuzzing

Black Box fuzzing

- Target: tasks
- Arbitrary messages with nosclient
 - Known format of the messages
 - We get a return code, and an actual response if successful
- → **Mutate** the message, **check** return code
 - If greater than 1, something happened

external/nos/host/generic/nugget/include/application.h

```
enum app_status {
 /* A few values are common to all applications */
 APP\_SUCCESS = 0.
 APP_ERROR_BOGUS_ARGS, /* caller being stupid */
 APP_ERROR_INTERNAL, /* application being stupid */
 APP_ERROR_TOO_MUCH, /* caller sent too much data */
 APP_ERROR_IO, /* problem sending or receiving data */
 APP_ERROR_RPC, /* problem during RPC communication */
 APP_ERROR_CHECKSUM,
                     /* checksum failed, only used within protocol */
 APP_ERROR_BUSY, /* the app is already working on a command */
 APP_ERROR_TIMEOUT, /* the app took too long to respond */
 APP_ERROR_NOT_READY, /* some required condition is not satisfied */
```

Implementation

- Plug libprotobuf-mutator¹ in nosclient
 - Very straightforward
 - o void Mutate(protobuf::Message* message, size_t max_size_hint);
- Basic corpus generation
 - Messages are quite simple
 - Start from empty ones, but add some non-trivial fields
- Store and triage inputs generating faulty states

Results

Firmware: 2020-09-25, 0.0.3/brick_v0.0.8232-b1e3ea340

- 2 buffer overflows (1 exploited for code exec)
- 4 null pointer dereferences
- 2 unknown bugs causing a reboot

Firmware: latest (at the time), 0.0.3/brick_v0.0.8292-b3875afe2

- 2 null-ptr deref still make the chip crash
- Bug reported → not a vulnerability

All of this after a few minutes of fuzzing...

Comments and limitations

- Bugs!
- Very simple to implement
- Decent performance: ~74 msg/sec
- Testing in real world
- Only "scratching the surface"
- Prone to false positives
- Detection is tricky
- X Risk of bricks

Bottom line: hard to know what's going on the target

Emulation-based fuzzing

Switching to emulation-based

- We know how the OS works.
- We can leak arbitrary memory with an exploit on an old firmware
 - Helps setting up memory
- With emulation, we control what is executed
 - Good feedback for a fuzzer

Emulating Titan M

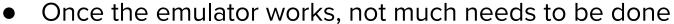
- Played with several frameworks
- Choice: Unicorn²
- Why?
 - Emulates CPU only
 - We do not care about full-system emulation
 - Easy to setup & tweak
 - Integrates nicely with AFL++



[2]: https://www.unicorn-engine.org/

Fuzzing with AFL++

- AFL++ in Unicorn mode
 - Instrument anything that can be emulated with Unicorn
 - Fuzz with the classic AFL experience



- place_input_callback to copy input sample
- Crashes detected at Unicorn errors (e.g. UC_ERR_WRITE_UNMAPPED)
- Custom mutators depending on needs
 - AFL_CUSTOM_MUTATOR_LIBRARY=<mutator.so>
 - AFL_CUSTOM_MUTATOR_ONLY=1 to use only that one

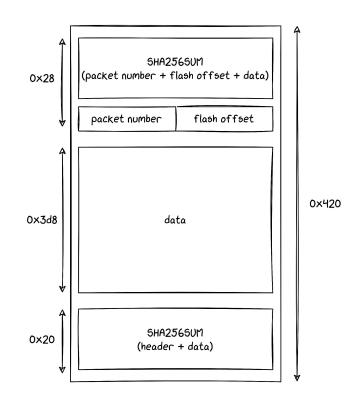


What to fuzz

- Pretty much anything!
- All you need is:
 - An entry point
 - Valid memory state
 - Registers set at the right values
 - One or more exit points
- Keep attack surface into account

SPI rescue feature

- SPI rescue allows to flash new firmware
 - No password required
 - Wipes user data
 - Can be triggered from bootloader
- Firmware sent as rec file



The Boot ROM

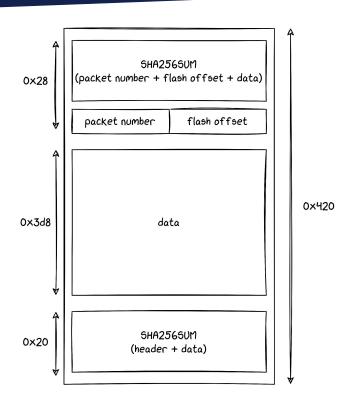
- Thanks to the 1-day exploit, we leaked the Boot ROM
- A bug there would be disastrous
- Not much code to test (only 16 KB)
- Idea: fuzz the image loader
 - We could flash them with SPI rescue

... no interesting results

- The function is simple, and not processing much
- Samples are just image headers

SPI rescue handler

- Focus on the rescue feature itself
- Are input files parsed and processed correctly?
- This time input is structured
 - Let's mutate it smartly :)
- We use FormatFuzzer⁴
 - Allows to generate and parse binary files
 - Follows the bt template format, from the
 010 editor
 - Requires a modified version of AFL++



... also this time, no bugs (but some interesting internals revealed)

Going back to the tasks

- Tasks use protobuf
- Rely again libprotobuf-mutator
 - With some tricks to embed the message name in the bytes it generates
- Focused on Identity and Keymaster
 - The largest and most complex tasks
 - We fuzzed Weaver too, but it is not as interesting
- First, can we find the same bugs we know about?

Yes! (apart from one...)

There is no free lunch

- Emulation is not a silver bullet!
- Embedded targets → hw-dependant code everywhere...
 - Lots of hooks
 - Code that can't be exercised
 - Especially true in system functions
- A bug doesn't always make Unicorn crash
 - No ASAN-like instrumentation
 - In-page overflows, off-by-ones won't be detected
- No full system emulation → miss some parts of code
 - No system state
 - The bug we missed makes the scheduler crash
 - ... and we don't emulate the scheduler ••

Tweaks

- Much more capabilities compared to pure black-box
- A few heuristics we implemented:
 - Monitor consecutive reads in the Boot ROM → spot buggy memcpy
 - Hook accesses to specific global buffers
 - Even more specific ones on different commands
- At the same time, everything comes at a cost
 - Hooks impact performance
 - In our case, not a big deal due to very specific harnesses

The vulnerability

CVE-2022-20233

- param_find_digests_internal
 - Checks digest tags in KeyParameter objects
- Out-of-bounds write of 1 byte to
 0x1
 - Can be repeated multiple times
 - Huge constraints on the offset
- Looks like a minor issue...

```
message KeyParameter {
   Tag tag = 1;
   uint32 integer = 2;
   uint64 long_integer = 3;
   bytes blob = 4;
}

message KeyParameters {
   repeated KeyParameter params = 1;
}
```

CVE-2022-20233

```
ldr.w
       r1,[r2,#-0x4]
ldr
        r3,[PTR_DAT_0005d808]; 0x20005
        r1, r3
cmp
        increment_loop_vars
bne
ldr
        r3,[r2,#0x0]
uxtb
        r0, r3
        r0,#0x4
cmp
bhi
       error_exit
        r1,#0x1
movs
lsl.w
        r0, r1, r0
        r0,#0x15
tst
beq
        error_exit
        r1, [r7, r3]
strb
```

CVE-2022-20233

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ldr.w
       r1,[r2,#-0x4]
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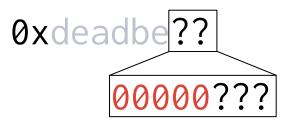
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0xdeadbeef

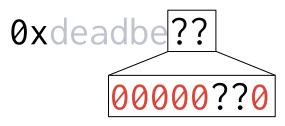
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```



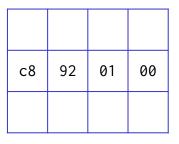
What can we do?

- Multiple ways to reach the vulnerable code
 - A few different command handlers call it
 - Different base addresses for the OOB-write
- Titan M's memory is completely static
 - All structures are always located at the same addresses
- Setting one byte can be enough to break the system

Our approach

- Generate all writable addresses
- Highlight them in Ghidra
- • ...

KEYMASTER_SPI_DATA



```
void * callback_addr

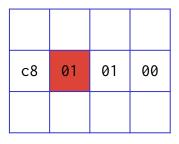
char * cmd_request_addr

char * cmd_response_addr
```

Our approach

- Generate all writable addresses
- Highlight them in Ghidra
- • ...

KEYMASTER_SPI_DATA



```
void * callback_addr

char * cmd_request_addr

char * cmd_response_addr
```

What to overwrite

KEYMASTER_SPI_DATA

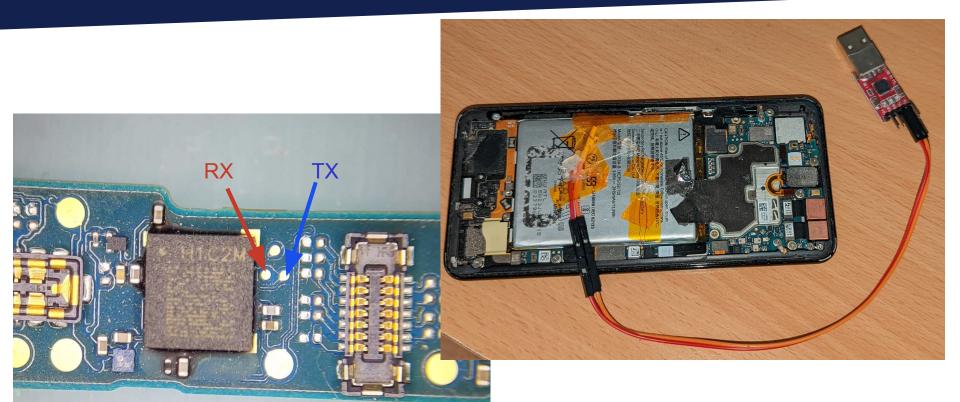
- Global structure
- Stores info about SPI commands
- cmd_request_addr: where to store incoming Keymaster requests
- $0x192c8 \rightarrow 0x101c8$



But first...

- Remainder:
 - Communication through nosclient
 - Send request using Android libs
 - Get a return code and (maybe) a response
 - A few logs on logcat
- What if we crash the chip?
 - Error code 2
- That's it
- Debugging an exploit is... challenging

Accessing the UART

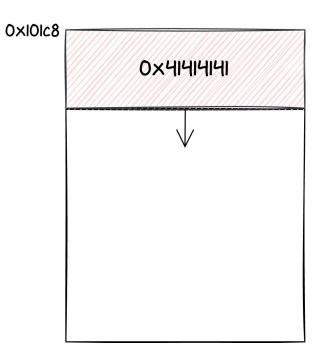


UART console

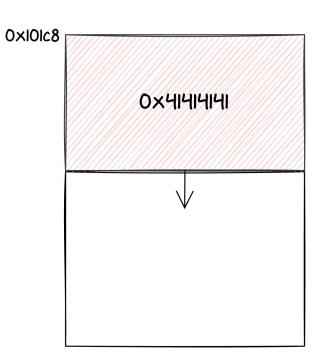
```
$ picocom /dev/ttyUSB0 -b 115200
[Image: RW A, 0.0.3/chunk ab7976980-a9084b7 2021-12-07
18:40:23 android-build]
[1.694592 Inits done]
[1.695460 update rollback mask: stop at 1]
[1.695884 \text{ gpio wiggling: AP EL2 LOW IRQ = 0}]
Console is enabled; type HELP for help.
>
> help
Known commands:
                                       taskinfo
                                                  version
 apfastboot
               history
                           repo
 board id
               idle
                           sleepmask
                                       timerinfo
 help
        reboot
                           stats trngstats
HELP LIST = more info; HELP CMD = help on CMD.
```

- Allows basic interaction
- Prints logs
 - Useful when exploiting

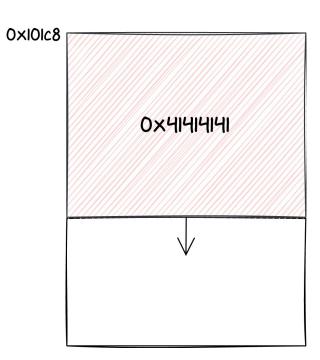
- Data doesn't seem to be used
- How do we hijack execution flow?
- Idea:
 - Send progressively bigger payloads
 - In parallel monitor the UART
 - ... and see what happens



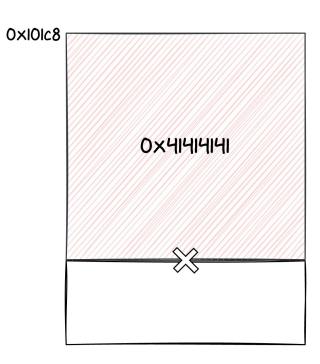
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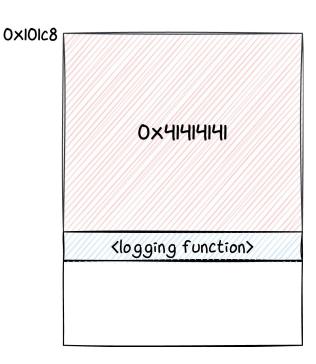
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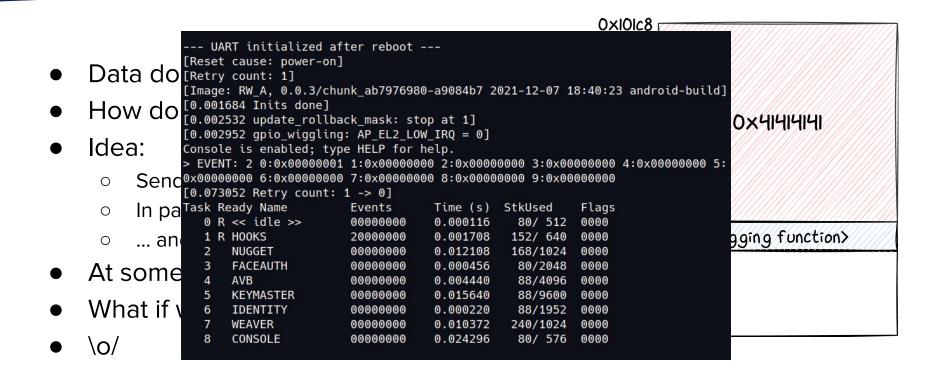


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- Data doesn't seem to be used
- How do we hijack execution flow?
- Idea:
 - Send progressively bigger payloads
 - In parallel monitor the UART
 - ... and see what happens
- At some point, the chip starts crashing
- What if we put a valid address at the end?





Exploiting

- Our guess:
 - We are actually in the stack of a task (idle)
 - We overwrite a function pointer that was pushed to the stack
 - At some point, the function jumps back to it
- From here on, things get complex
 - No space to write a ROP chain there
 - We need to move \$sp
- In the end, we send another command to complete the exploit
- Blogpost arriving soon :)

Impact

- Control the execution flow of the chip
 - We are not able to reconfigure the MPU
 - ... but we can do pretty much anything using ROP
- We implemented again a leak command
 - This time based on a 0-day
 - Data is not erased by the downgrade like before!
 - We can leak all the secrets stored in the chip's memory

```
sargo:/data/local/tmp # ./nosclient leak 0x0 0x10
00 00 02 00 99 14 00 00 b9 3e 00 00 b9 3e 00 00
```

Impact

Can we leak strongbox keys?

StrongBox

- StrongBox: hardware-backed version of Keystore
 - Generate, use and encrypt cryptographic material
- Titan M does not store keys
 - Key blobs encrypted with a Key Encryption Key
 - This KEK is derived in the chip from various internal elements
 - Key blobs are sent to the chip to perform crypto operations
 - root can use any key, but not extract it

Strongbox

KEKs are derived from a **key ladder**

- Still quite mysterious since we did not reverse it
- It uses
 - An internal root key
 - Not readable from the Titan M firmware
 - A Root Of Trust provided by the bootloader at first boot
 - A salt that is randomly generated when RoT is provisioned
- → We can leak most of the secrets, but not the key ladder root key

Strongbox

There are 3 commands to use strongbox keys:

- BeginOperation
 - Contains the keyblob and the characteristics of the key
 - The chip will decrypt the keyblob
 - And save it for later into a fixed address
- UpdateOperation
 - Contains the data on which the operation is performed
 - Return the output bytes
- FinishOperation
 - Contains the data on which the operation is performed
 - Return the output bytes
 - End the operation

Leak strongbox keys

Our strategy:

- 1. Get the keyblob from the device
 - Stored in /data/misc/keystore/persistent.sqlite
- 2. Forge a *BeginOperation* request
- 3. Leak the decrypted key from the chip memory

```
sargo:/data/local/tmp # ./nosclient leak_kb
- Key name: strongbox (size: 128)
sargo:/data/local/tmp # ./nosclient leak_kb -k strongbox
f3 7d 3d 7d ca 56 5e a0 18 ff 83 76 19 39 eb c1
```

Conditions

- Ability to send commands to the chip
 - Being root
 - Or direct access to the SPI bus
- Access to the keyblobs
 - Being root
 - Or find a way to bypass FBE...

Mitigation

```
KeyGenParameterSpec spec = new KeyGenParameterSpec.Builder("key_name",
   KeyProperties.PURPOSE_ENCRYPT | KeyProperties.PURPOSE_DECRYPT)
    .setBlockModes(KeyProperties.BLOCK_MODE_CBC)
    .setEncryptionPaddings(KeyProperties.ENCRYPTION_PADDING_PKCS7)
    .setIsStrongBoxBacked(true)
    .setUserAuthenticationRequired(true)
```

Conclusion

Conclusion

- Fuzzing allowed us to find more bugs
- With black box, you easily get the surface bugs
- Emulation-based fuzzing is particularly effective of such target
 - Yet few tricks are required to optimize the results
- We found a critical 0-day
 - Allowed us to execute code on the chip
 - Permit to leak anything from the chip's memory
- A single software vulnerability is enough to leak strongbox keys

Tools & resources:

https://github.com/quarkslab/titanm

Thank you!

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Quarkslab