



Fault Injection Attacks on Secure Automotive Bootloaders

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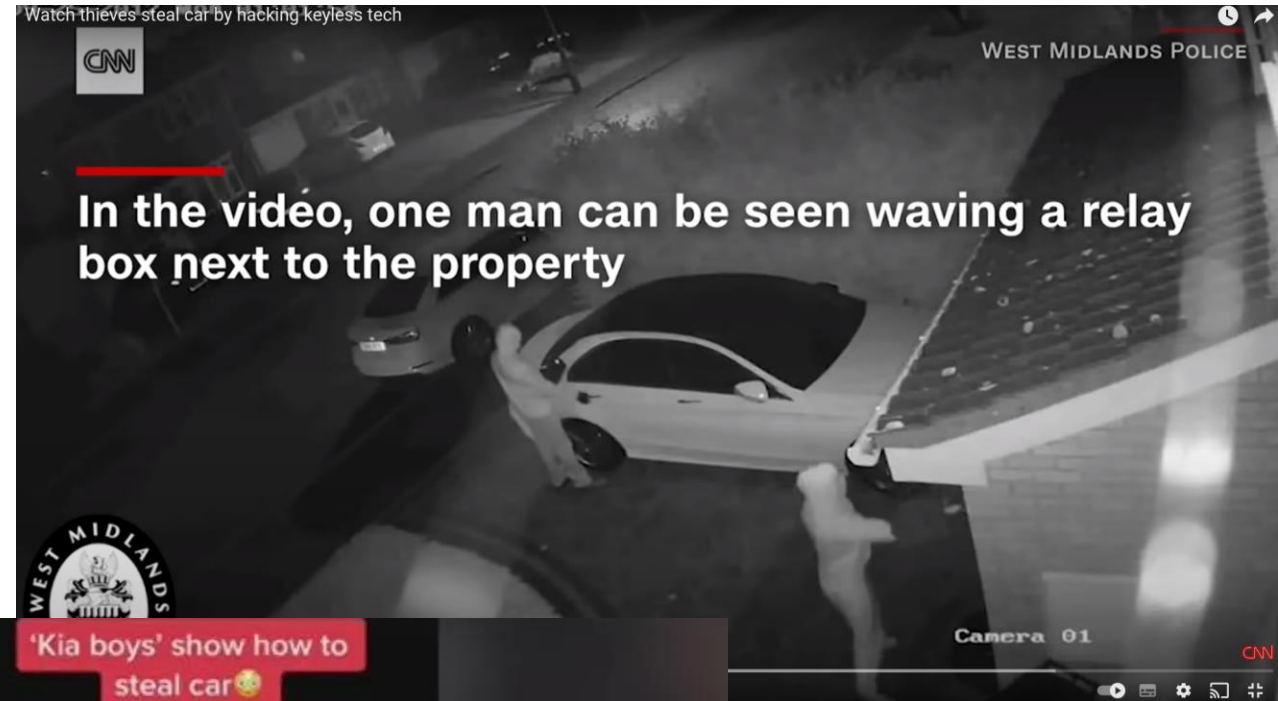
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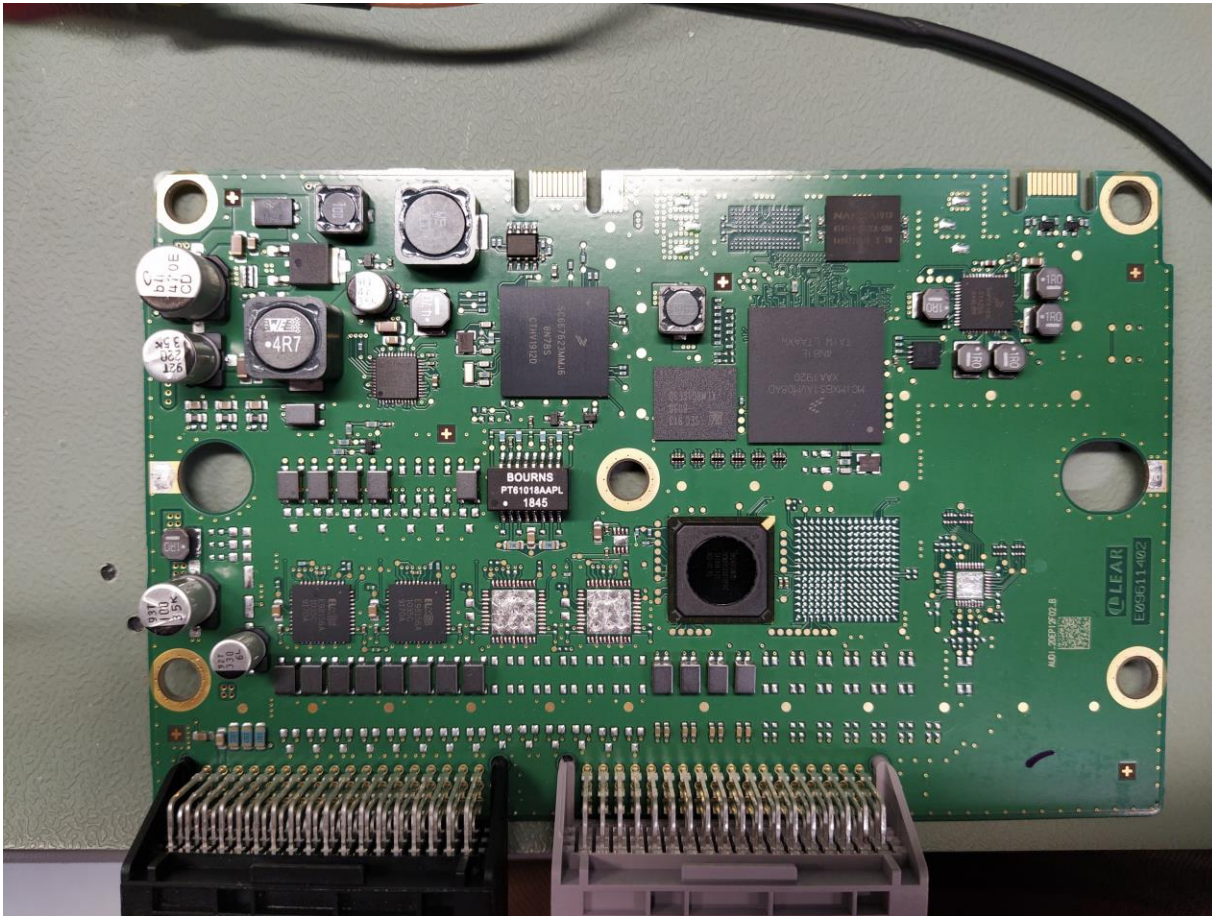
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Threat Model for HW Attacks in Automotive

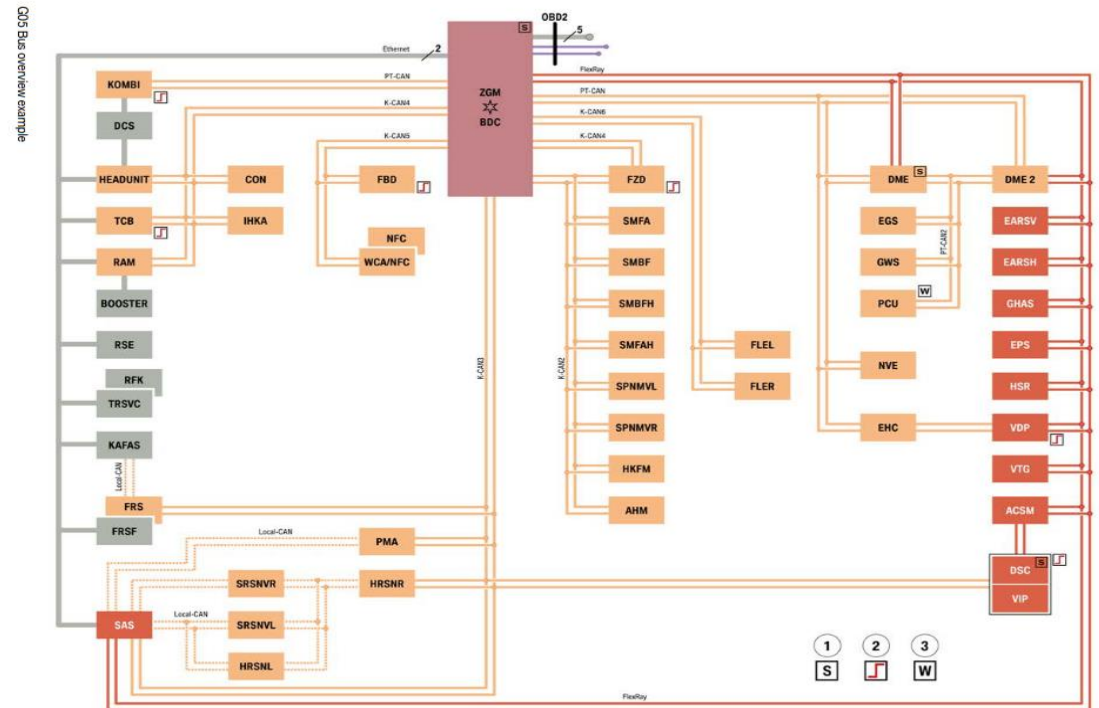
- Vehicle Theft (entire cars)
 - Break immobilizers
- Stolen ECUs aftermarket
 - Virgin ECUs
- Chip-Tuning
- Feature on Demand
- Mileage manipulation
- Ad-Blue manipulation
- E-Fuel detection



The target:



- Gateway-ECU
- Root of the Network
- Trust anchor for certain services



Safe and "Secure" microcontrollers



Q Search

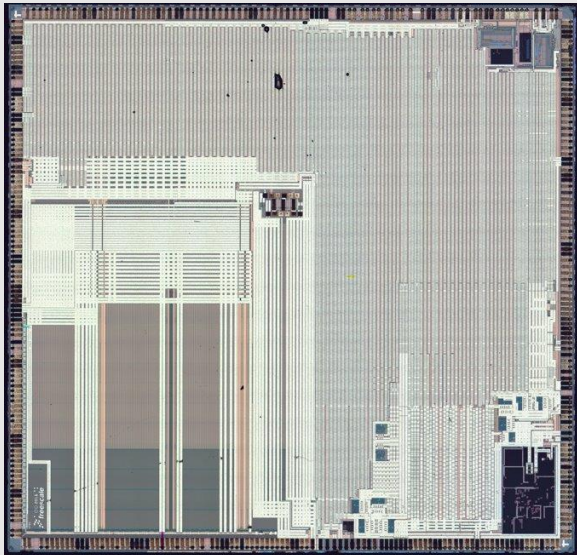
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LANGUAGE ▾



Ultra-Reliable MPC574xB/C/G MCUs for Automotive and Industrial Control and Gateway

MPC574xB-C-G [Receive alerts](#) ⓘ



Silicon of the MPC5748G, courtesy of Texplained

[Resources](#) ⓘ

[Training](#)

[Support](#)

[BUY/PARAMETRICS](#)

[PACKAGE/QUALITY](#)



The MPC574xB/C/G family of MCUs (eg. MPC5746C, MPC5748G) provides a highly integrated, **safe and secure** single-chip solution for next-generation central body control, gateway and industrial applications.



What makes an MCU "Automotive"?

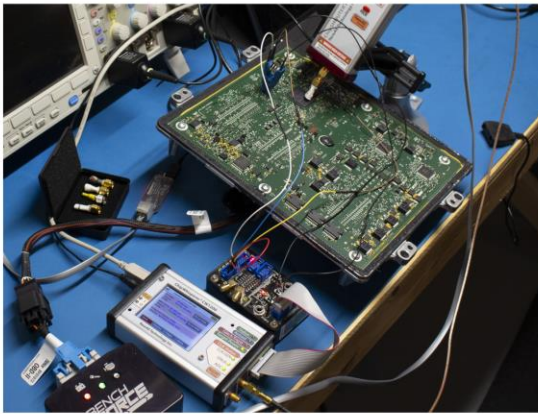
- It is tolerant to a wide range of temperatures.
- It can withstand high voltage transients.
- It doesn't break easily in the presence of electromagnetic pulses.



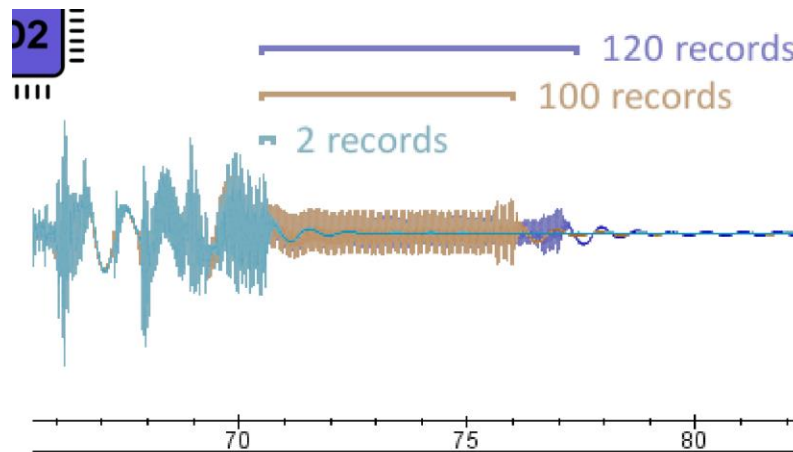
Abbildung		
Herst.-Teilnr.	ATSAME51J19A-AFT	ATSAME51J19A-AU
Herst.	Microchip Technology	Microchip Technology
Lieferant	Microchip Technology	Microchip Technology
DK-Teilnr.	ATSAME51J19A-AFTTR-ND ATSAME51J19A-AFTCT-ND ATSAME51J19A-AFTDKR-ND	ATSAME51J19A-AU-ND
Beschreibung	IC MCU 32BIT 512KB FLASH 64TQFP	IC MCU 32BIT 512KB FLASH 64TQFP
Preis	6,62000 €	5,89000 €
Lagerbestand	0	116
Mindestmenge	1	1
Serie	Automotive, AEC-Q100, SAM E51	SAM E51

Existing glitching attacks on ECUs

- Safety \neq Security from Riscure (Attacking DCF Record Loading)
- BAM BAM by Colin o'Flynn
- Nasahl and Timmers used glitching attacks on an evaluation setup to obtain code execution on an AUTOSAR-based demonstration ECU



(c) E41 ECU "In-Situ" Target



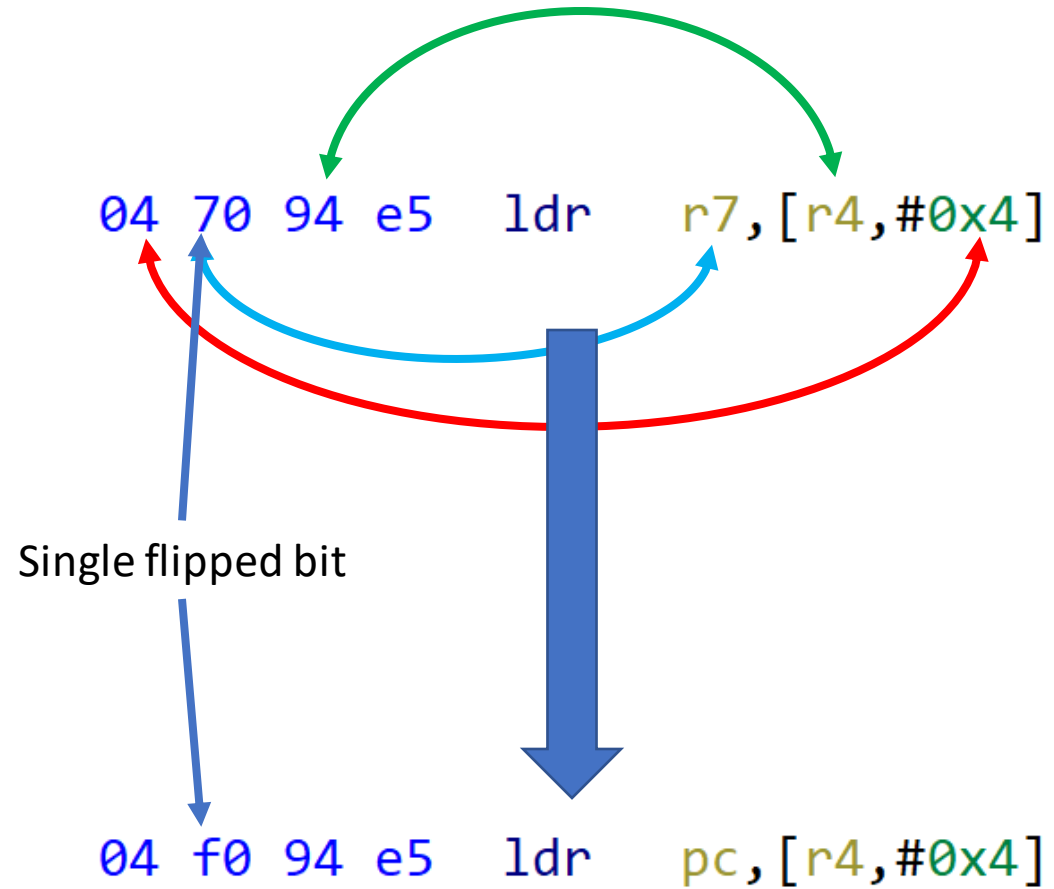
```
<memcpy>:  
mov    ip, r0  
orr.w  r3, r1, r0  
ands.w r3, r3, #3  
bne.n  8008300 <memcpy+0xe8>  
subs   r2, #64 ; 0x40  
bcc.n  80082ac <memcpy+0x94>  
ldr.w  r3, [r1], #4  
str.w  r3, [r0], #4  
subs   r2, #64 ; 0x40  
bcs.n  8008228 <memcpy+0x10>  
adds   r2, #48 ; 0x30  
bcc.n  80082d4 <memcpy+0xbc>
```



```
<memcpy>:  
mov    ip, r0  
orr.w  r3, r1, r0  
ands.w r3, r3, #3  
bne.n  8008300 <memcpy+0xe8>  
subs   r2, #64 ; 0x40  
bcc.n  80082ac <memcpy+0x94>  
ldr.w  pc, [r1], #4  
str.w  r3, [r0], #4  
subs   r2, #64 ; 0x40  
bcs.n  8008228 <memcpy+0x10>  
adds   r2, #48 ; 0x30  
bcc.n  80082d4 <memcpy+0xbc>
```

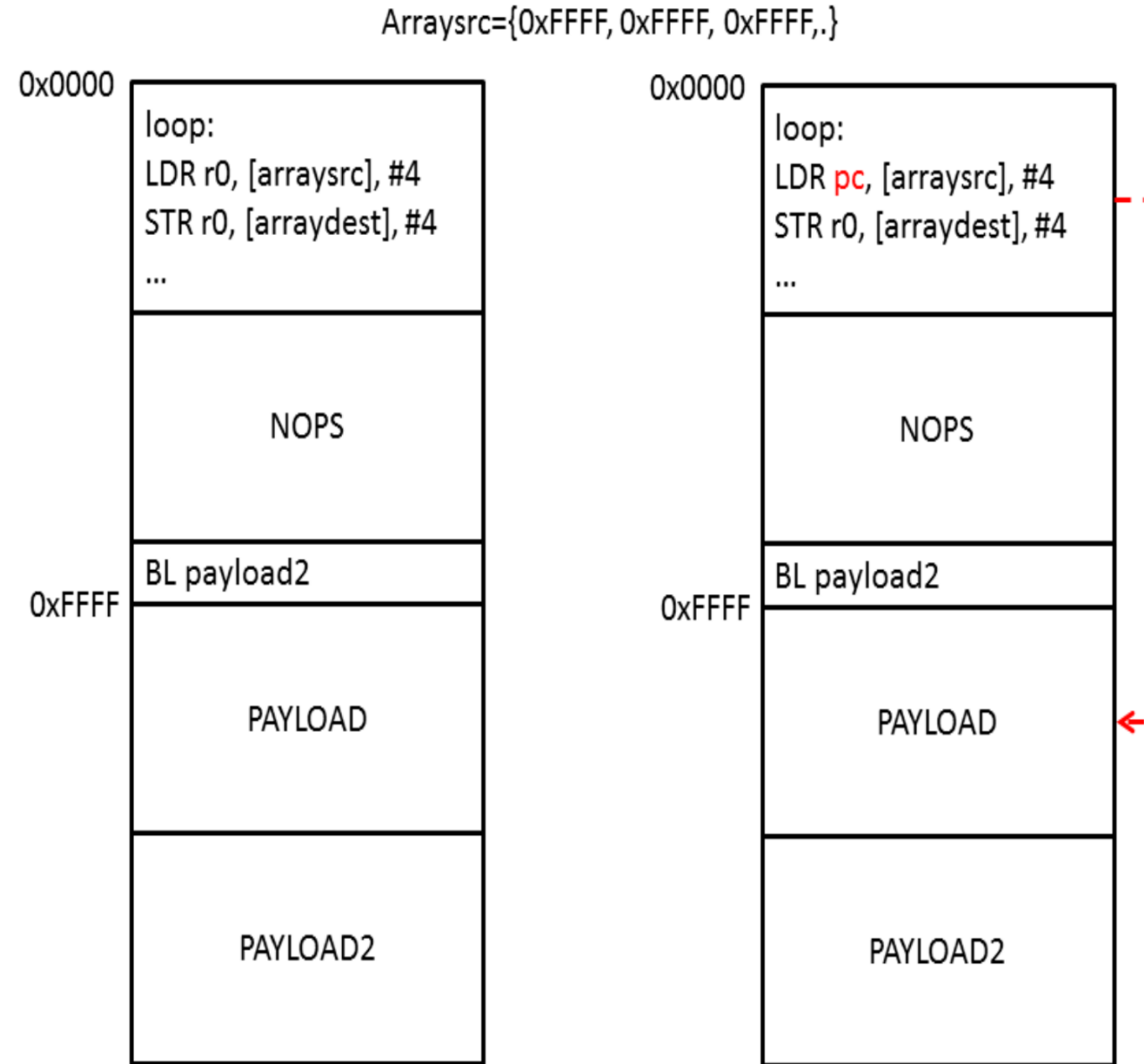
Fig. 3. Glitch injection moment during the *memcpy* function.

Controlling PC by Fault Injection on ARM



Wild Jungle Jumps

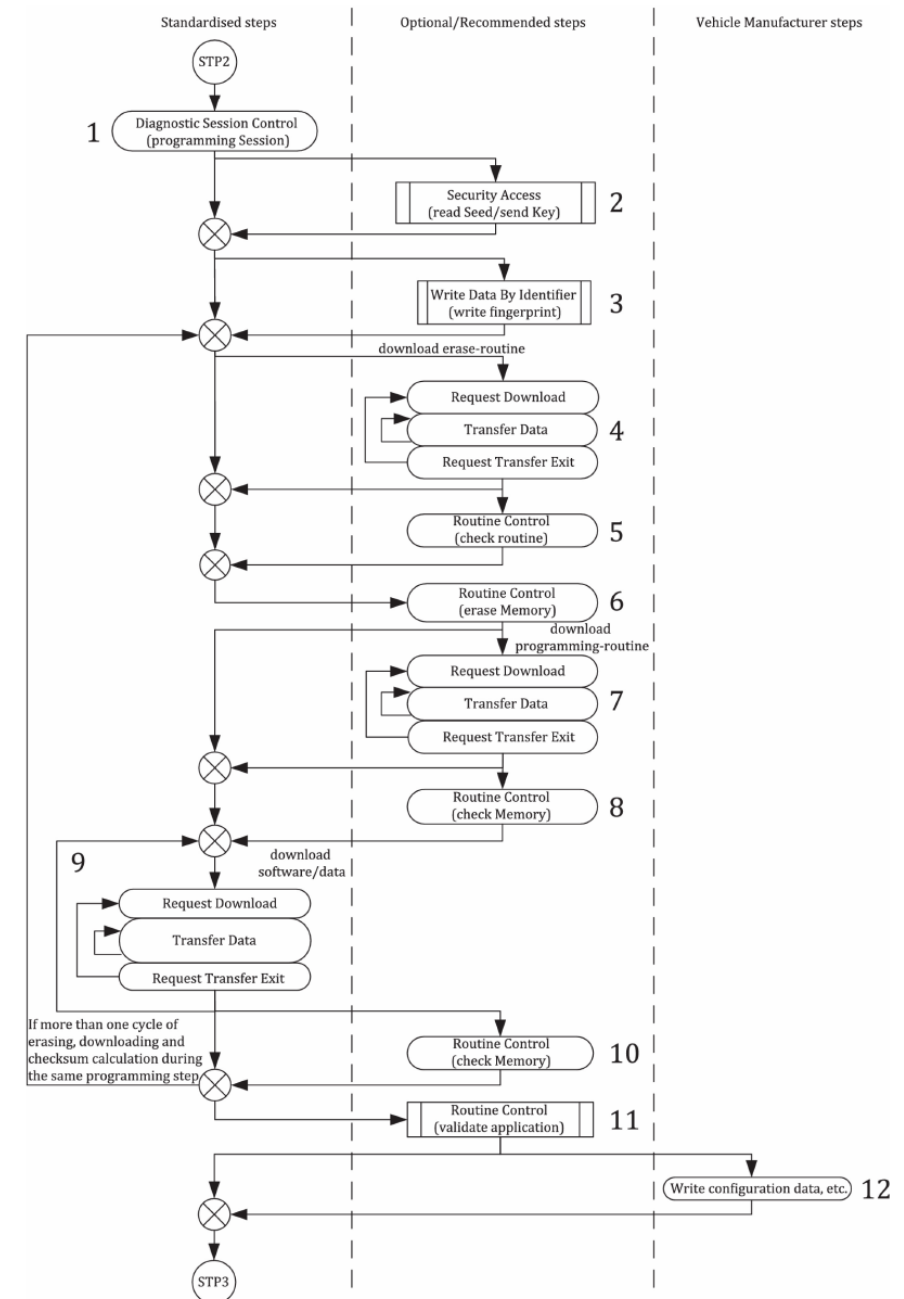
- "Until now, wild jungle jumps were only exploitable in laboratory environments and considered impossible in practice" - Spensky et al. *Glitching demystified: Analyzing control-flow-based glitching attacks and defenses*



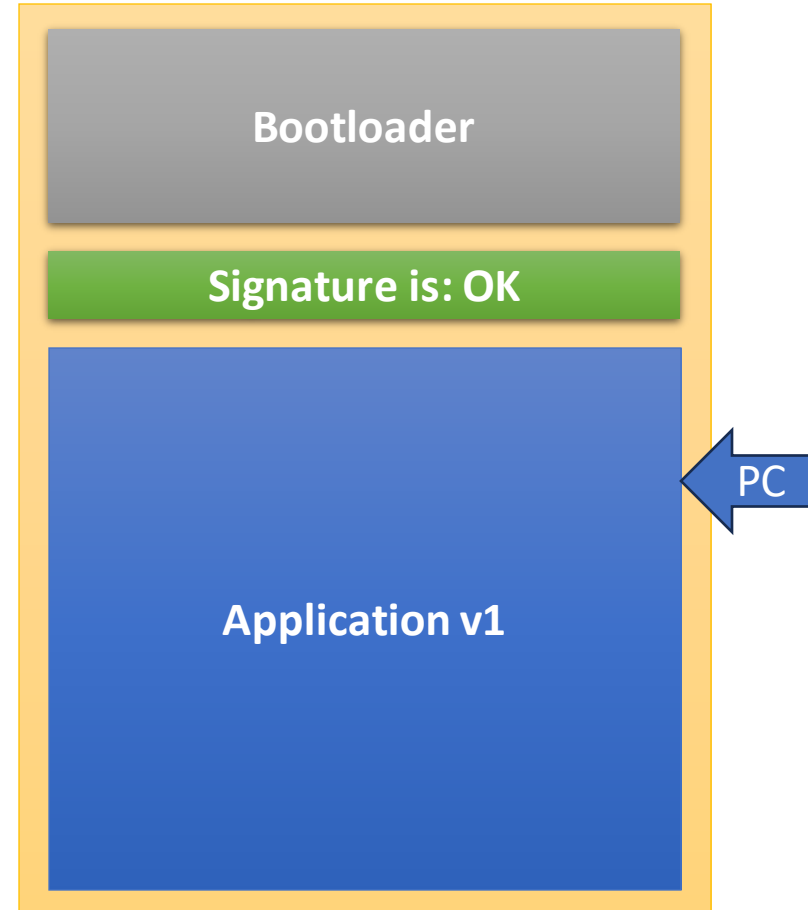
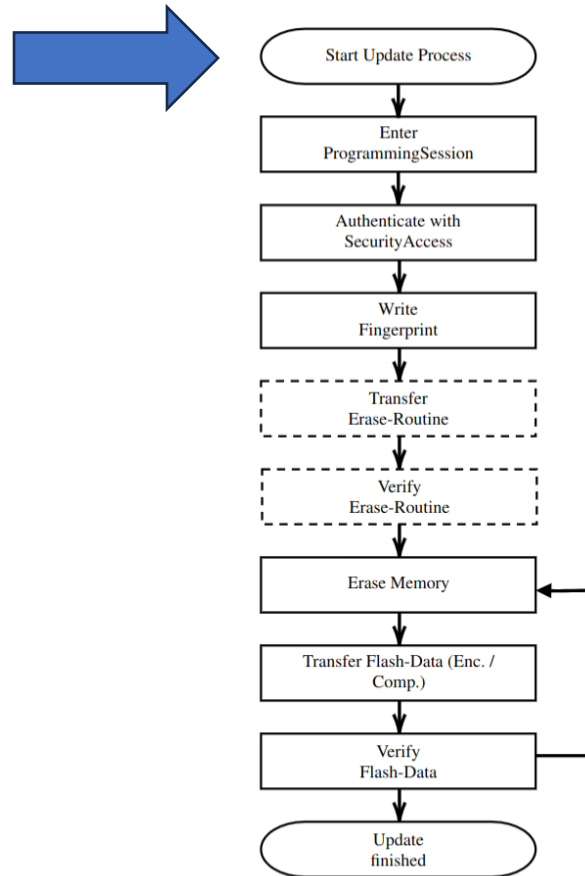
Picture by James Gratchof – Proving the wild jungle jump

UDS / ISO 14229-1:2020

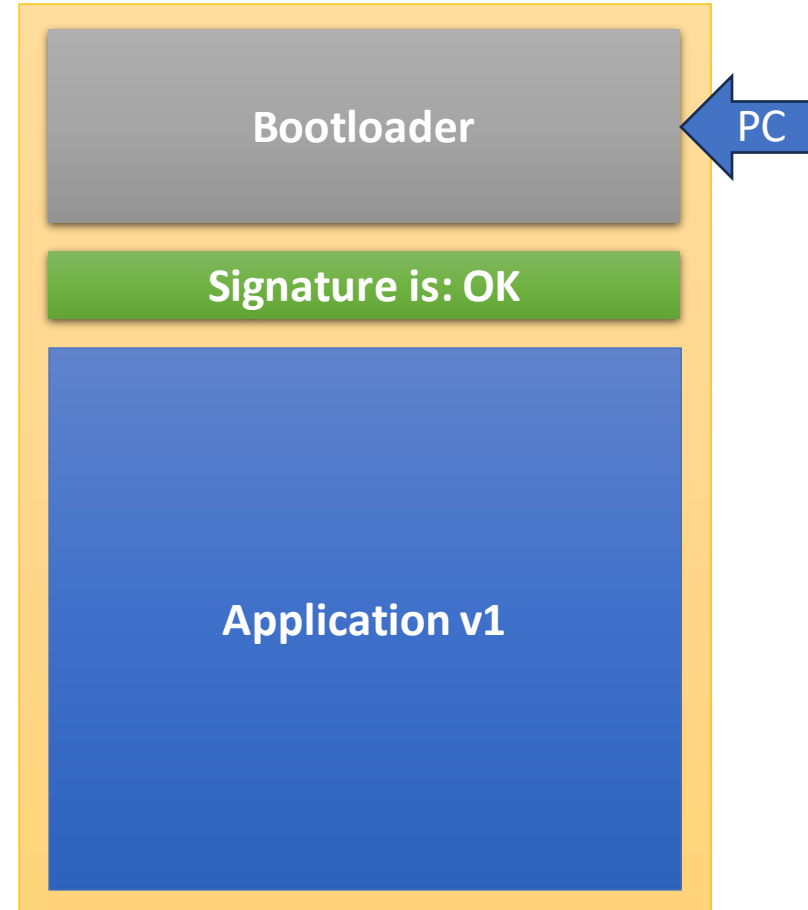
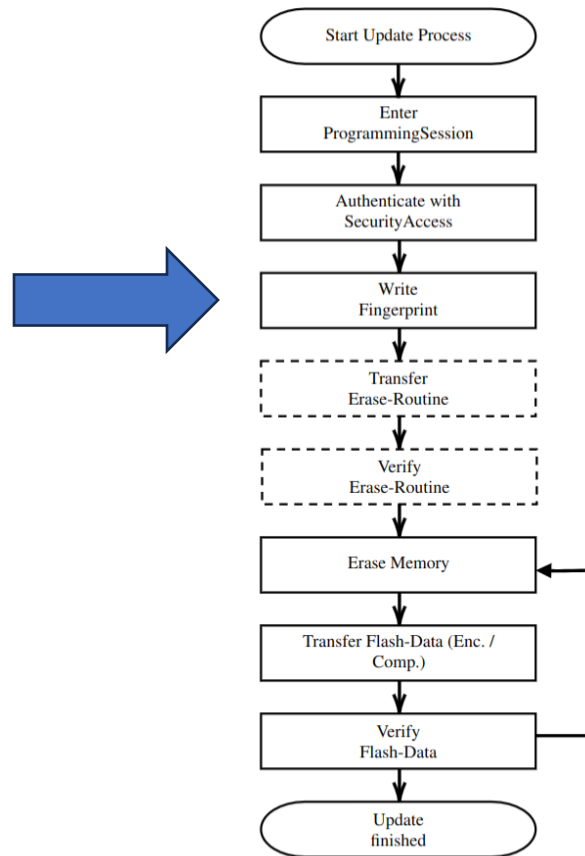
- Communication with ECUs is mostly standardized
- Modern ECUs supports UDS (Unified Diagnostic Services)
 - Configuration of ECUs
 - Reading Information and DTCs
 - Erasing / Flashing
- UDS defines Flashing-Procedure
 - Small variations for each individual OEM



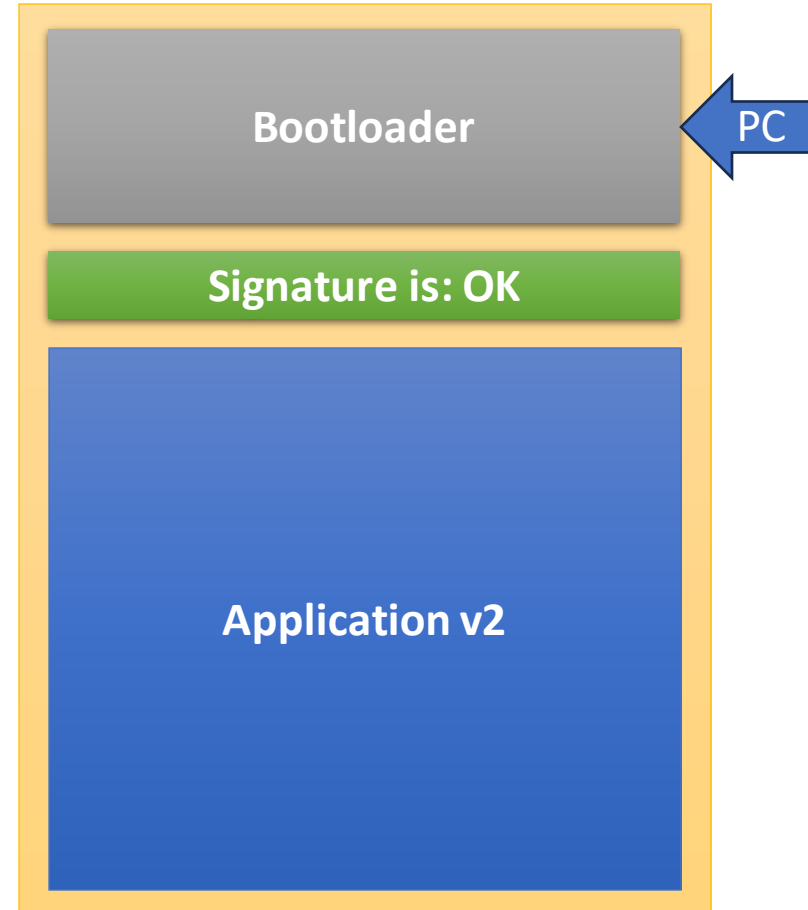
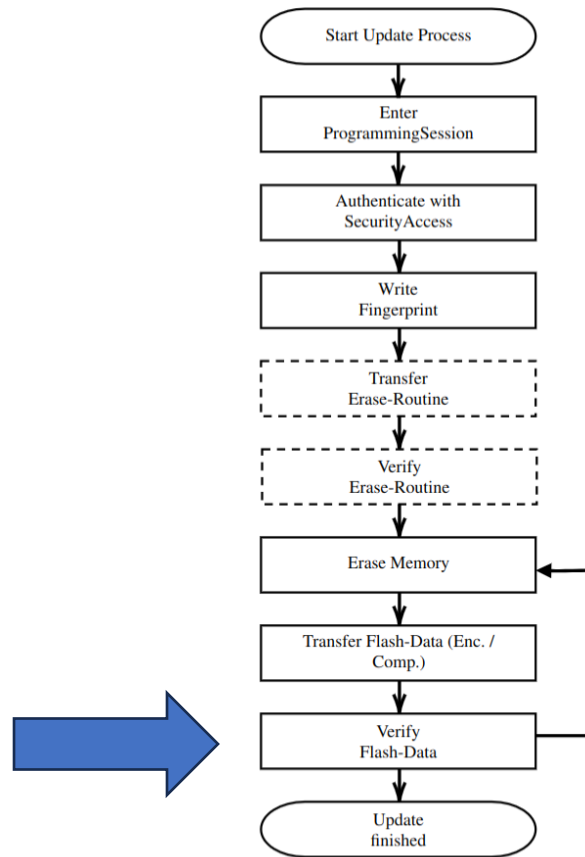
UDS Update Process



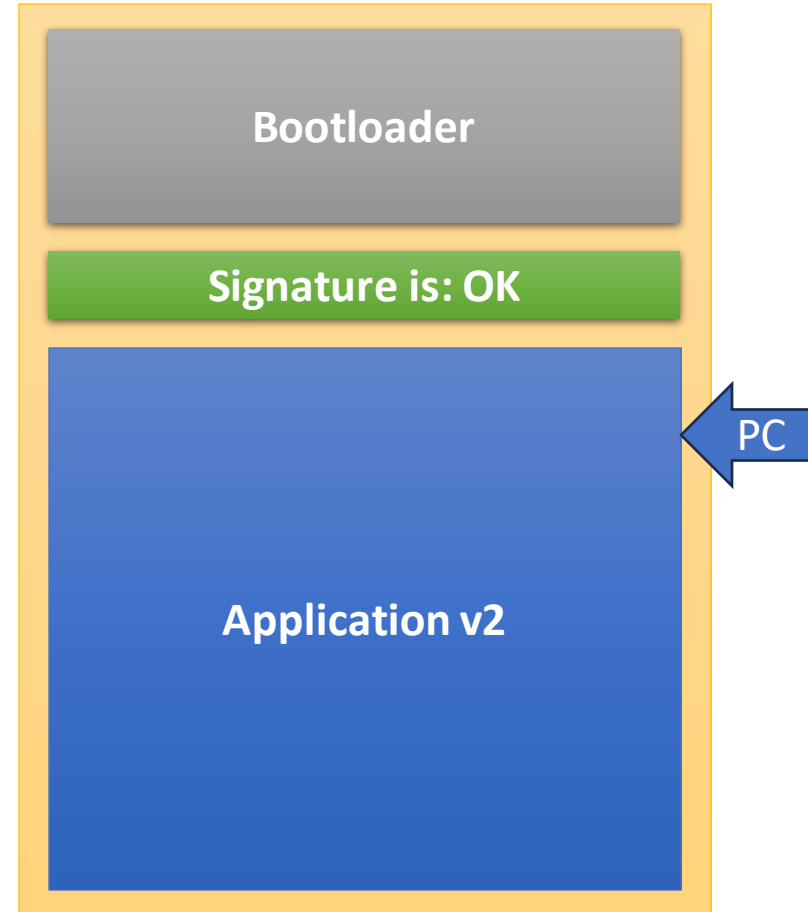
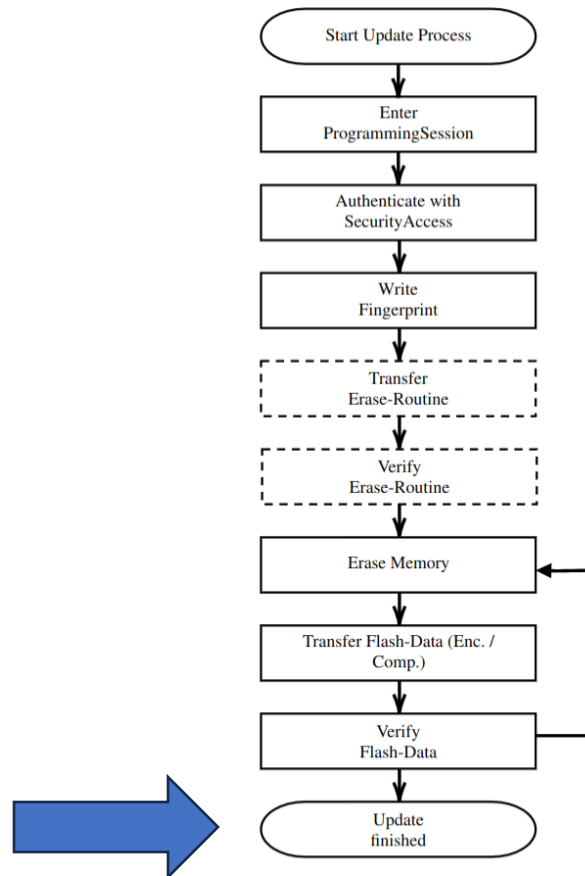
UDS Update Process



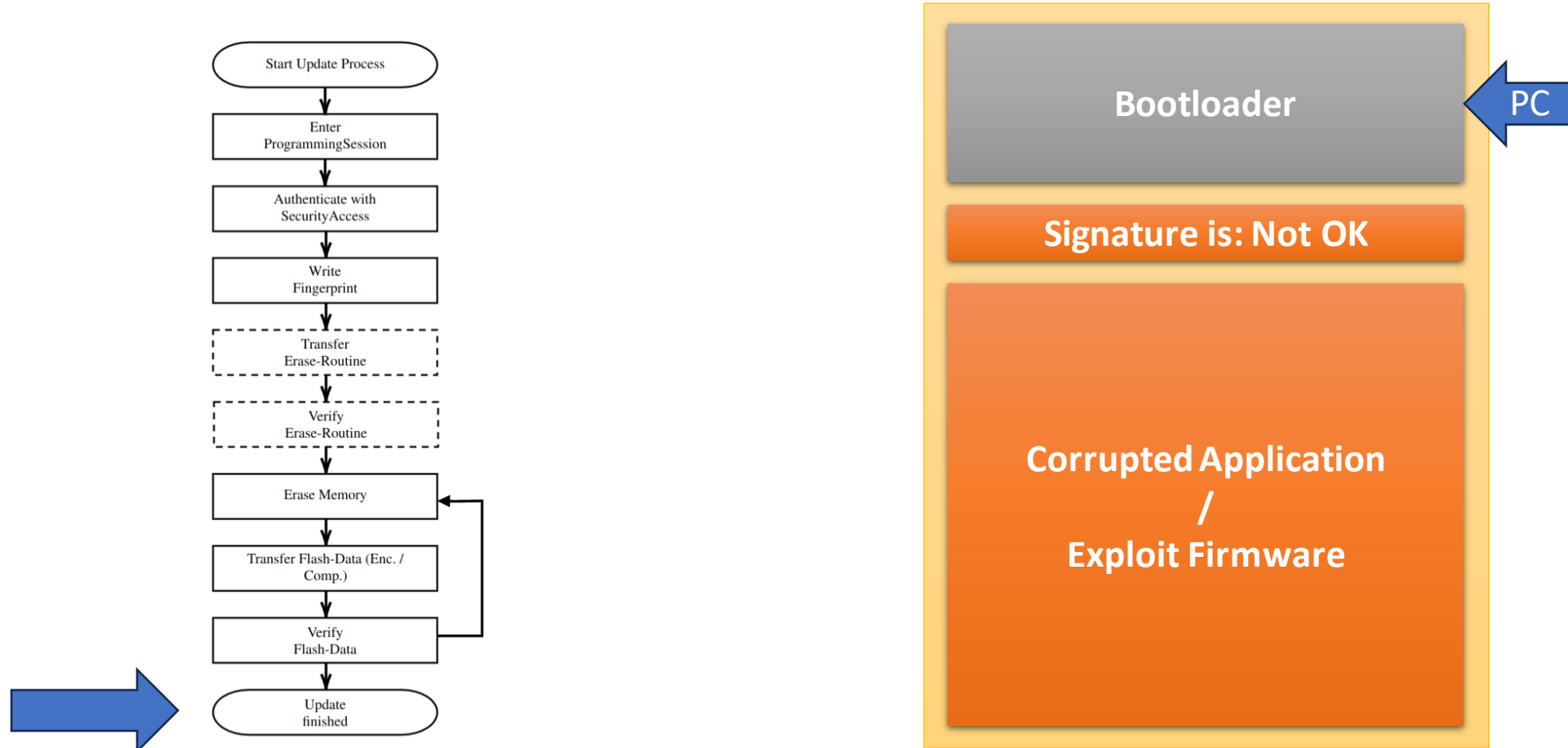
UDS Update Process



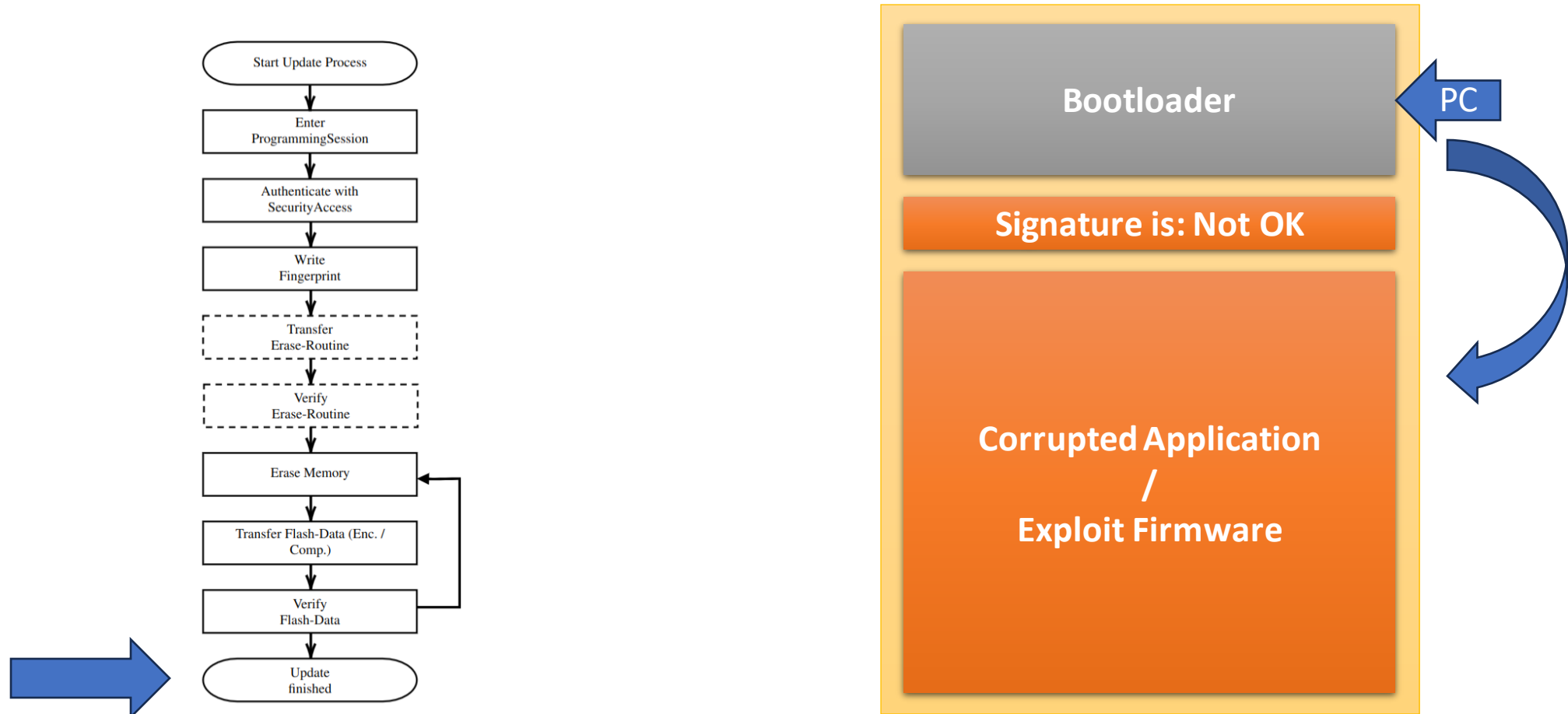
UDS Update Process



If the application signature verification fails, the bootloader will not jump to the application

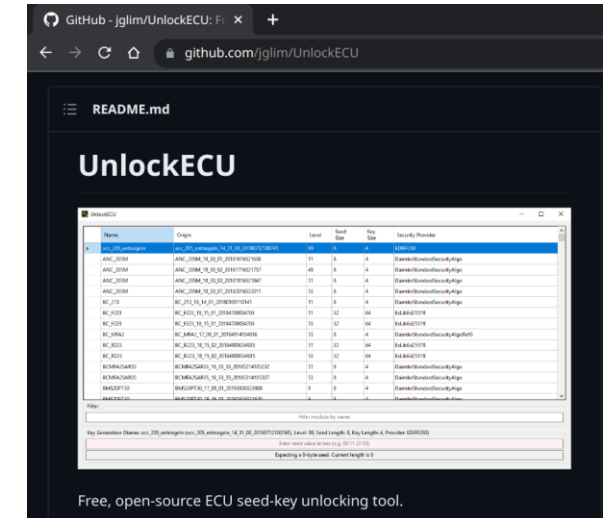
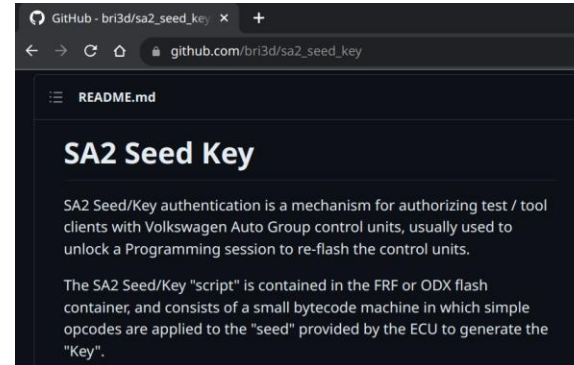


The attack: Use fault injection to jump from bootloader to unauthenticated payload

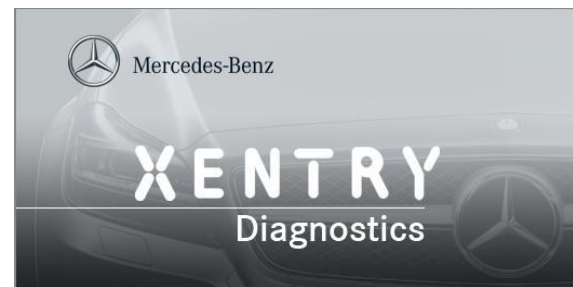


UDS Security Access

- Security Access Algorithms are available on GitHub



- OEM-Tools leak on shady internet forums



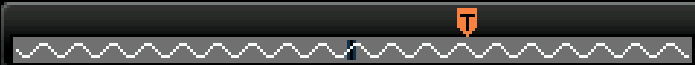
- Many Security Access implementations are leaked or broken or easy to overcome

RIGOL

STOP

H 100ns

500MSa/s
3.00M pts



D -1.00000000ms

T 2.50 V

Horizontal



Period



Freq



Rise Time



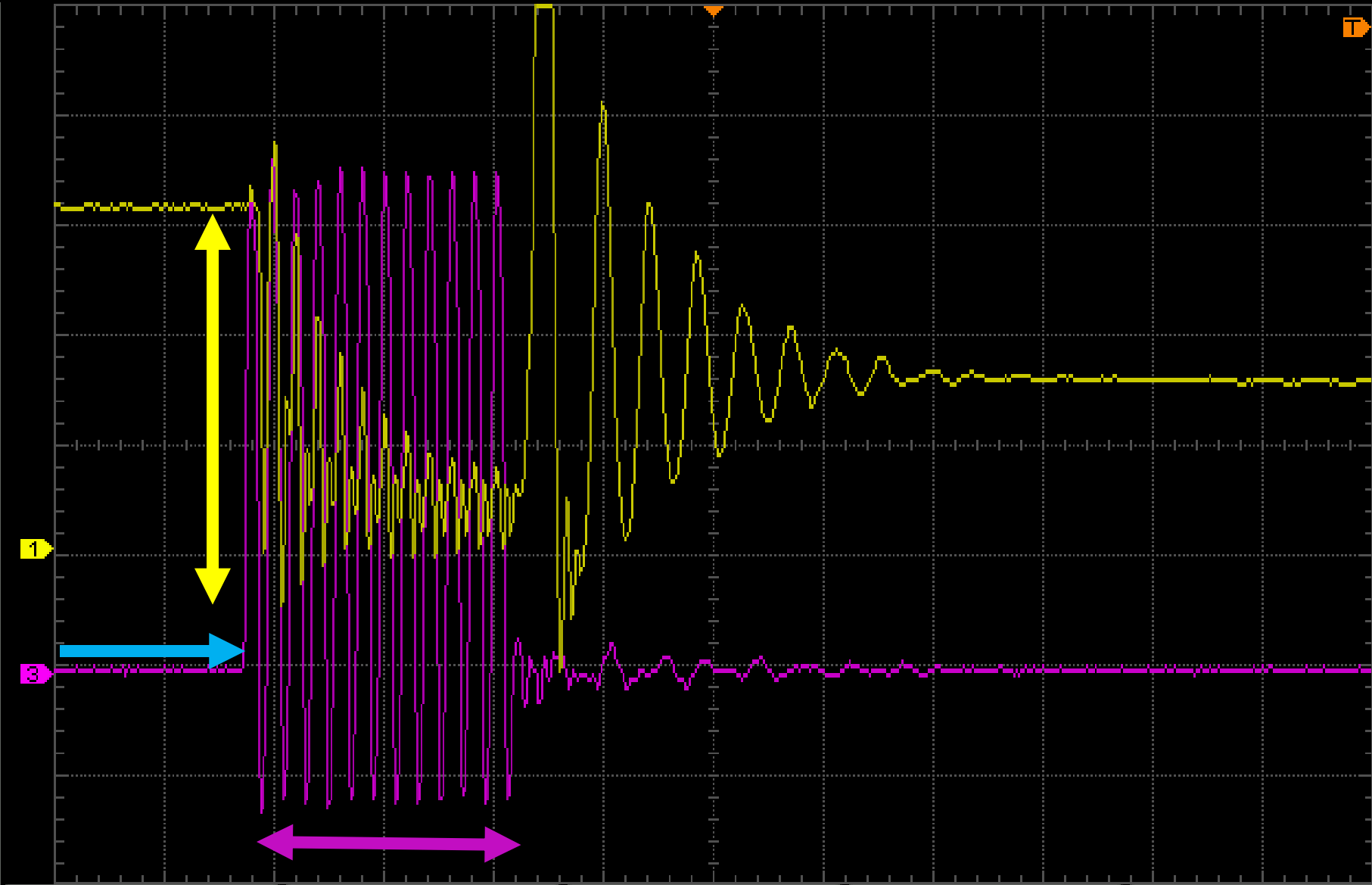
Fall Time



+Width



-Width



Period=***** +Width=***** Ampl=***** Vmax=***** Vmin=*****

1 = 1.00 V

2 = 2.00 V

3 = 1.00 V

4 = 2.00 V

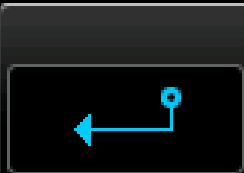
Save

Save

New File

NewFolder

Delete



EMFI parameters (search space)

- **Injection coil:** (shape, size, number and direction of turns),
- **Position** (x, y, z) in space of the injection coil,
- **Duration** of the activation of the coil,
- **Voltage** across the coil (aka across the injector reservoir capacitor),
- **Offset** from trigger signal,
 - if the target firmware has deterministic execution time, this is equivalent to choosing which instruction to attack!
- **Memory** / state of the target
 - Depends on the messages exchanged before the fault.
- And other environmental factors that can't be accounted for on stage.

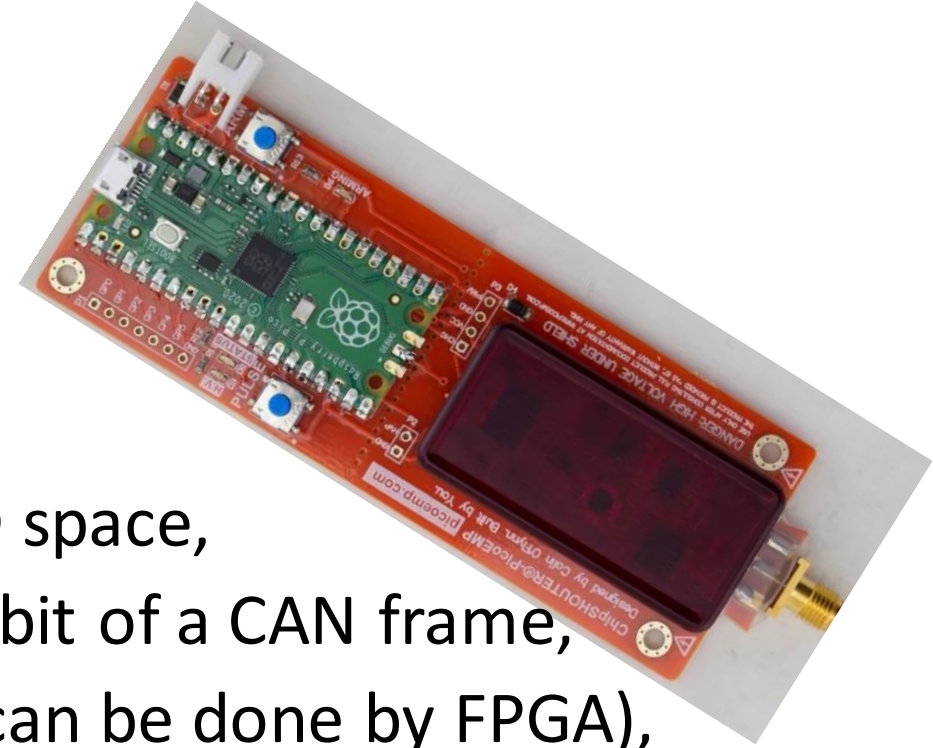
EMFI parameters (search space)

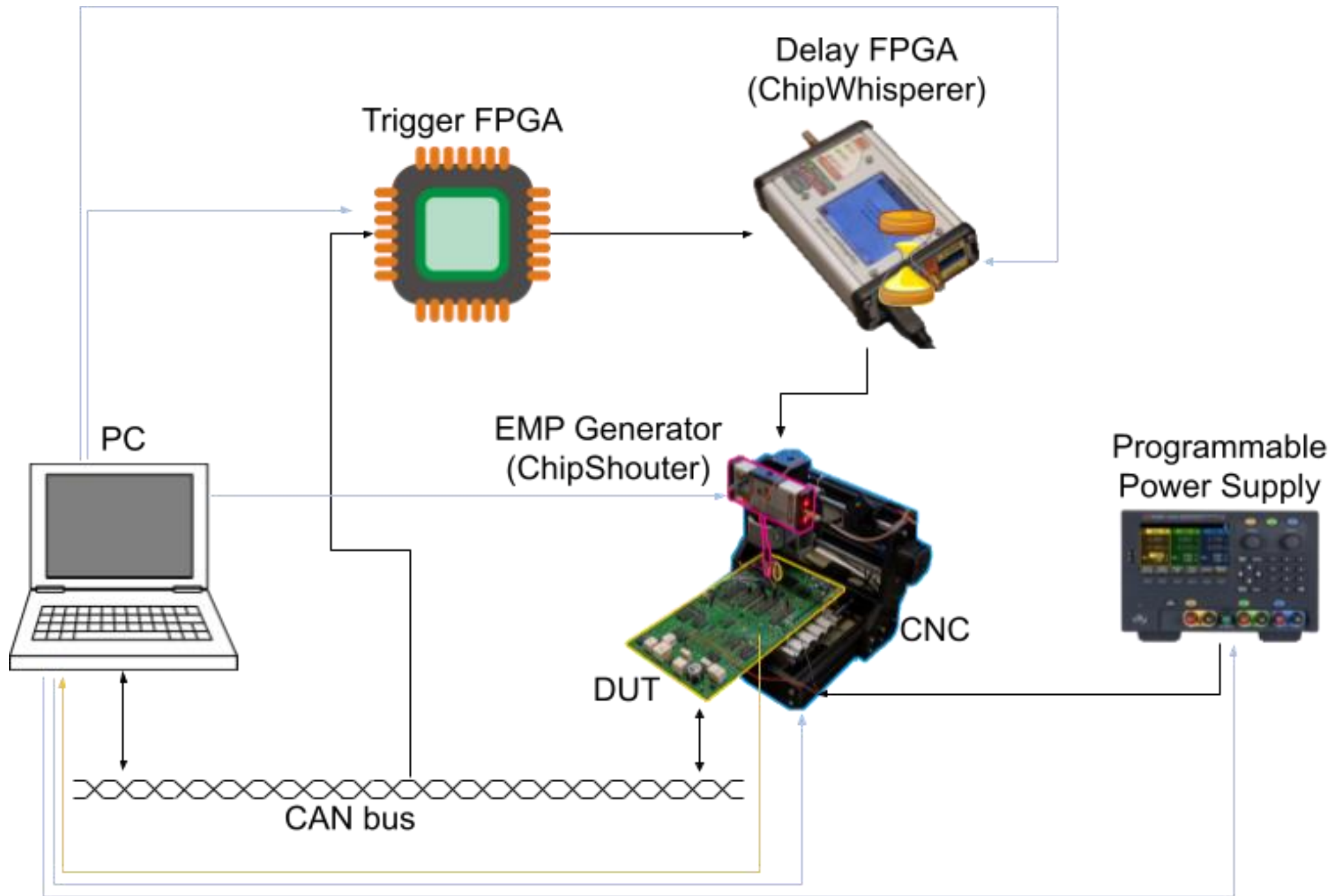
- **Injection coil:** (shape, size, number and direction of turns),
 - **Position** (x, y, z) in space of the injection coil,
 - **Duration** of the activation of the coil,
 - **Voltage** across the coil (aka across the injector reservoir capacitor),
- These don't depend on the target software, only on the hardware
- **Offset** from trigger signal,
 - if the target firmware has deterministic execution time, this is equivalent to choosing which instruction to attack!
 - **Memory / state** of the target
 - Depends on the messages exchanged before the fault.

EMFI Fault setup

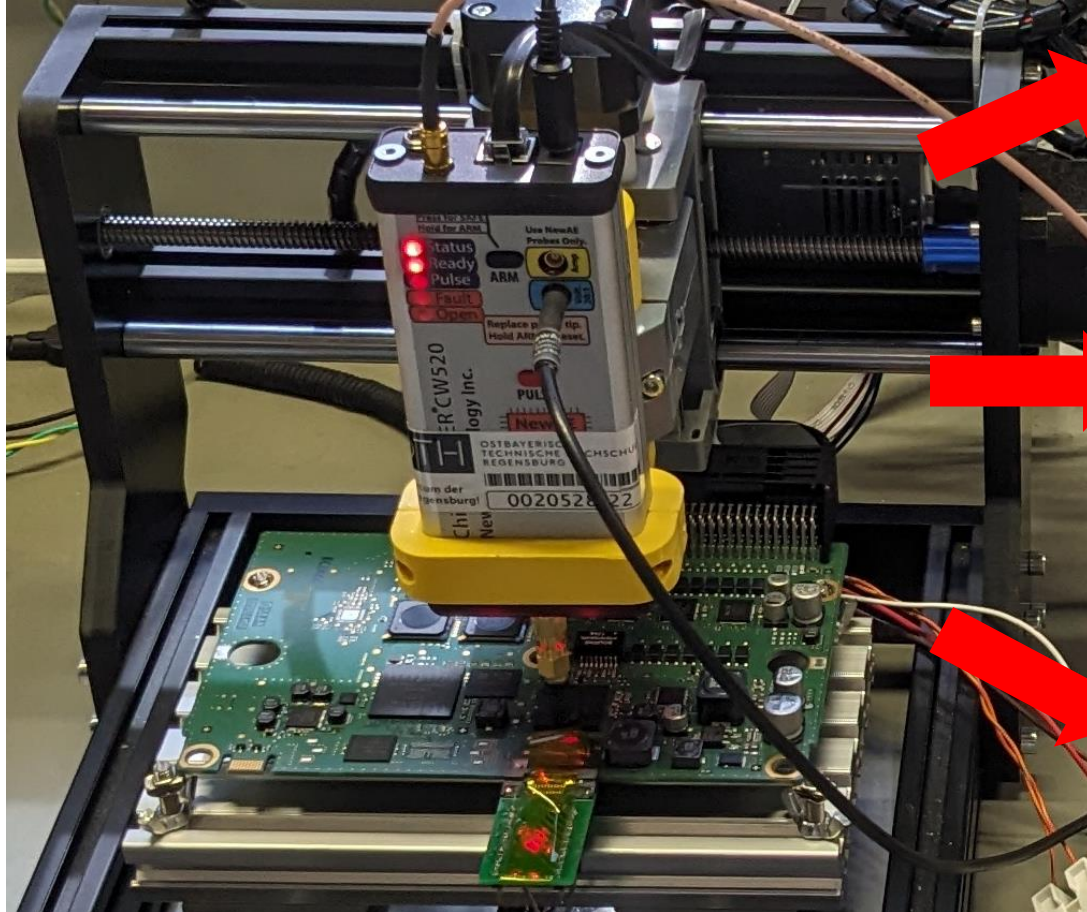
- **ChipSHOUTER**: generates the EMP,
- **CNC Mill**: Positions the injection coil in the 3D space,
- **Generic FPGA**: Precisely triggers on a specific bit of a CAN frame,
- **ChipWhisperer**: Delays the trigger (optional, can be done by FPGA),
- **Programmable supply**: to power-cycle the target when it crashes
- **CAN interface**: to transfer the exploit and bring the ECU to a specific state
- **UART interface**: to get feedback from the target

Total cost: ~5000\$ (can be reduced to ~300\$ by using PicoEMP)





Fault Outcomes



- Normal Response

- Corrupted CAN response

- ECU resets, no response

- Emission of an exception Stack Dump over UART

Machine Check Exception

Exception number: 1
Exception address: 0105D1EE
Stack pointer: 40006F98

R0	010F2FB8	R8	400070EC	R16	00000000	R24	400070EC
R1	40006F98	R9	013996A8	R17	00000000	R25	4004FAD8
R2	013DF918	R10	00000005	R18	00000000	R26	00000002
R3	02029200	R11	FFF1E400	R19	00000000	R27	00000002
R4	0000FFF1	R12	400070DC	R20	00000000	R28	0000E400
R5	00000000	R13	4001DD90	R21	00000000	R29	0000FFF1
R6	010F3130	R14	00000000	R22	00000000	R30	40007090
R7	0000FFF1	R15	00000000	R23	00000000	R31	4003EFA8

XER 00000000 CR 80000000 LR 010F2FB8
USPRG0 00000000 CTR 010F2EF4 IP -----

SPRG0 00000000 SRR0 013D1FD6 IVPR 01000100 MSR 00000200
SPRG1 400200C8 SRR1 02029200 DEAR 00000000 PVR 81530000
SPRG2 00000000 CSSR0 00000000 ESR 00000000
SPRG3 00000000 CSSR1 00000000 MCSR 00088008
MCSSR0 0105D1EE MCAR 00000078
MCSSR1 02021200
PID0 00000000

PIR 00000000

S T A C K T R A C E

> 0x010F2FB8
> 0x010F307A
> 0x010F1F1E
> 0x011281FC

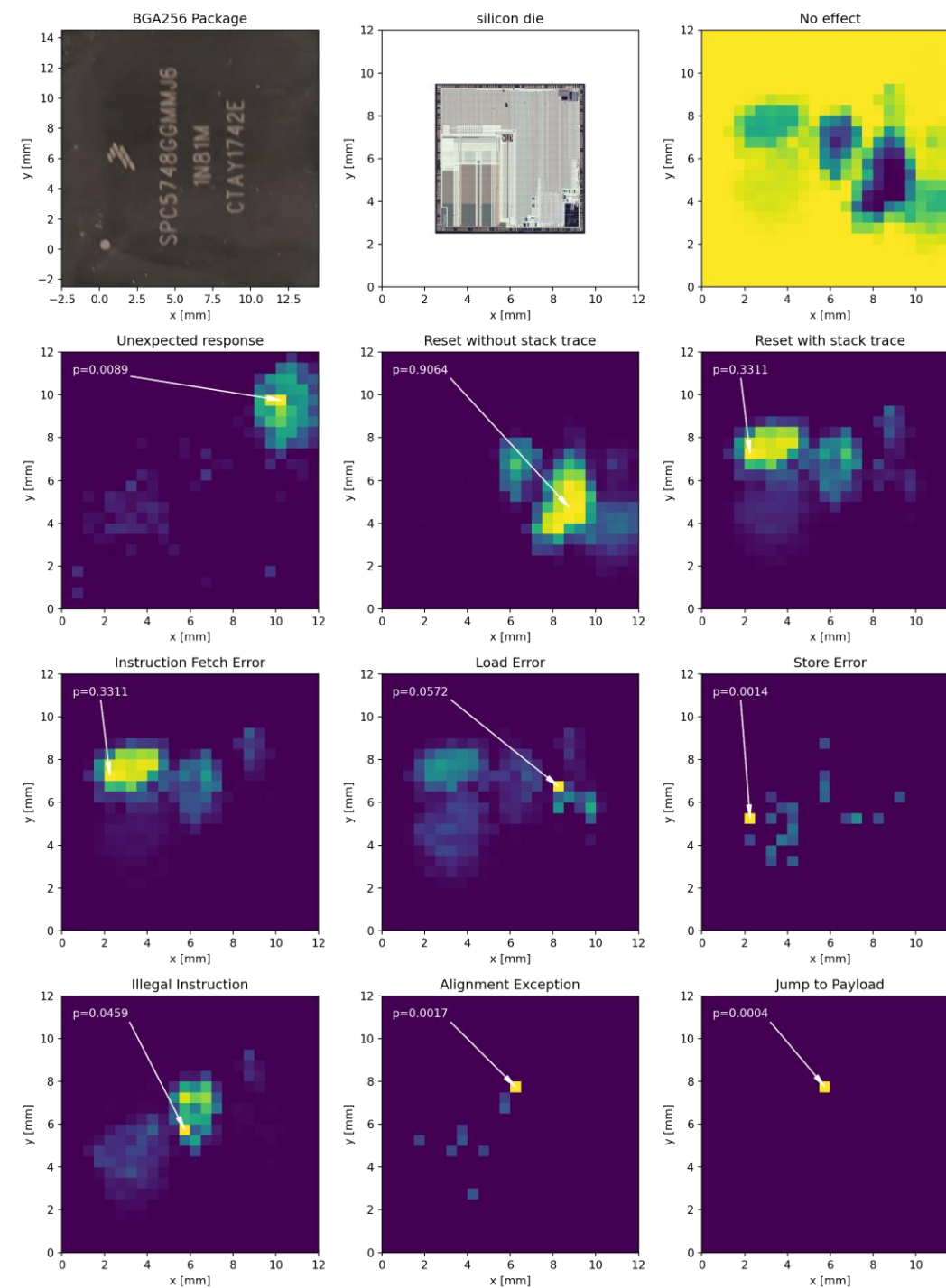
...

Example of a stack trace

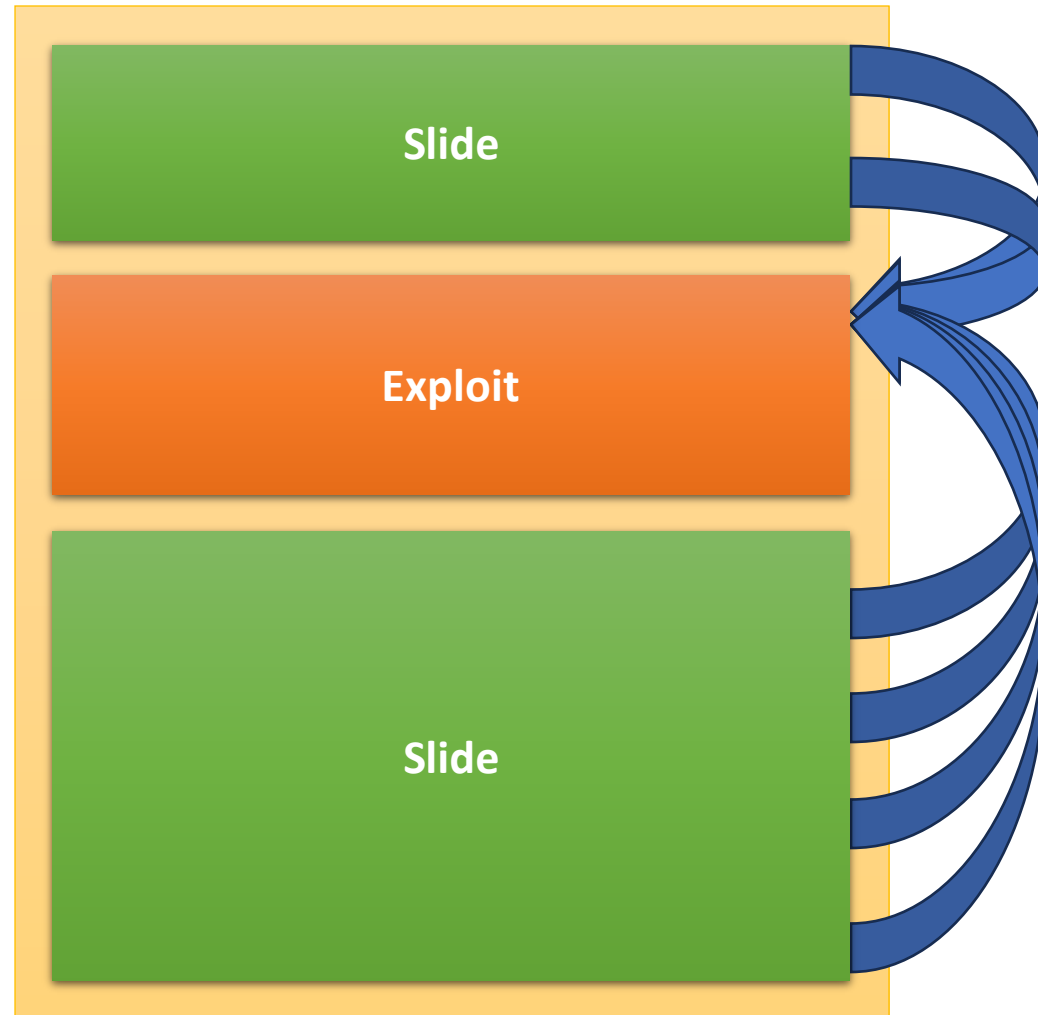
If the ECU doesn't emit stack traces, it is usually possible to source the same component or a similar one to program with a toy example firmware and find most fault parameters

Search Algorithm Optimizations

- Some parameters take longer to change (due to physical constraints)
- Some feedbacks correlate better with code execution than others
- Interrupt handlers are used as a feedback channel to rate glitches



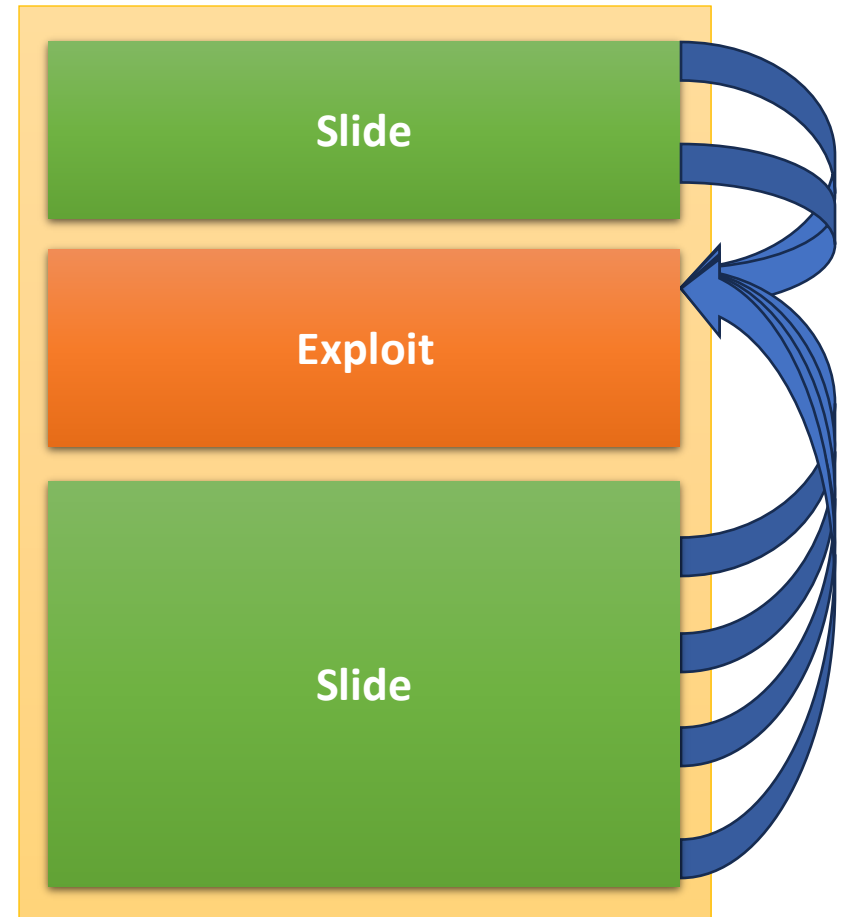
Ensure most of the unsigned firmware is composed of NOP slides / jumps to the exploit



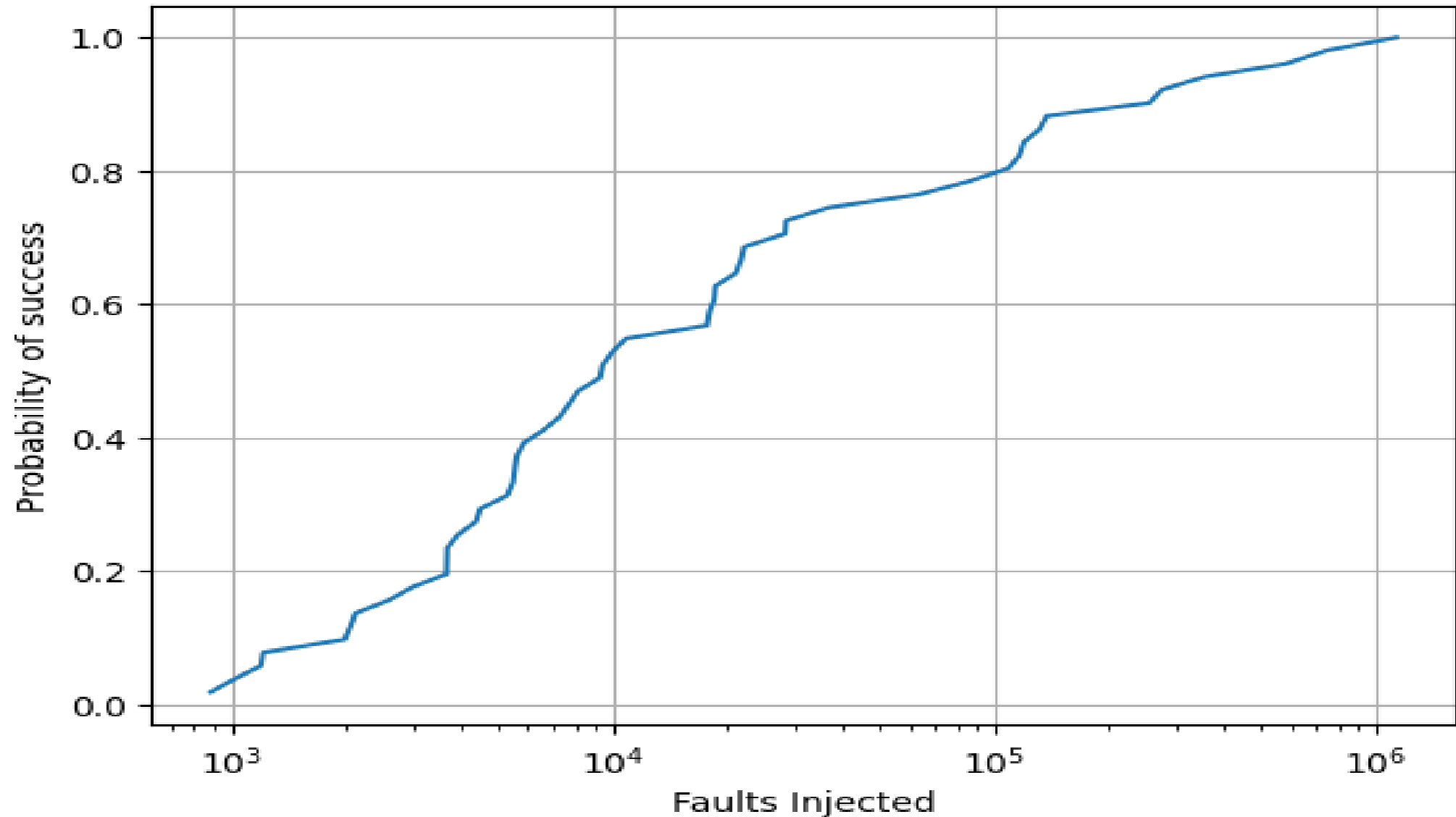
Structure of the exploit firmware

```
rept 1000
rept 113
    se_nop // 2 bytes
endr
    e_b _start // 4 bytes
endr
_start:
    // The actual exploit code is written here
rept 2000
rept 113
    se_nop // 2 bytes

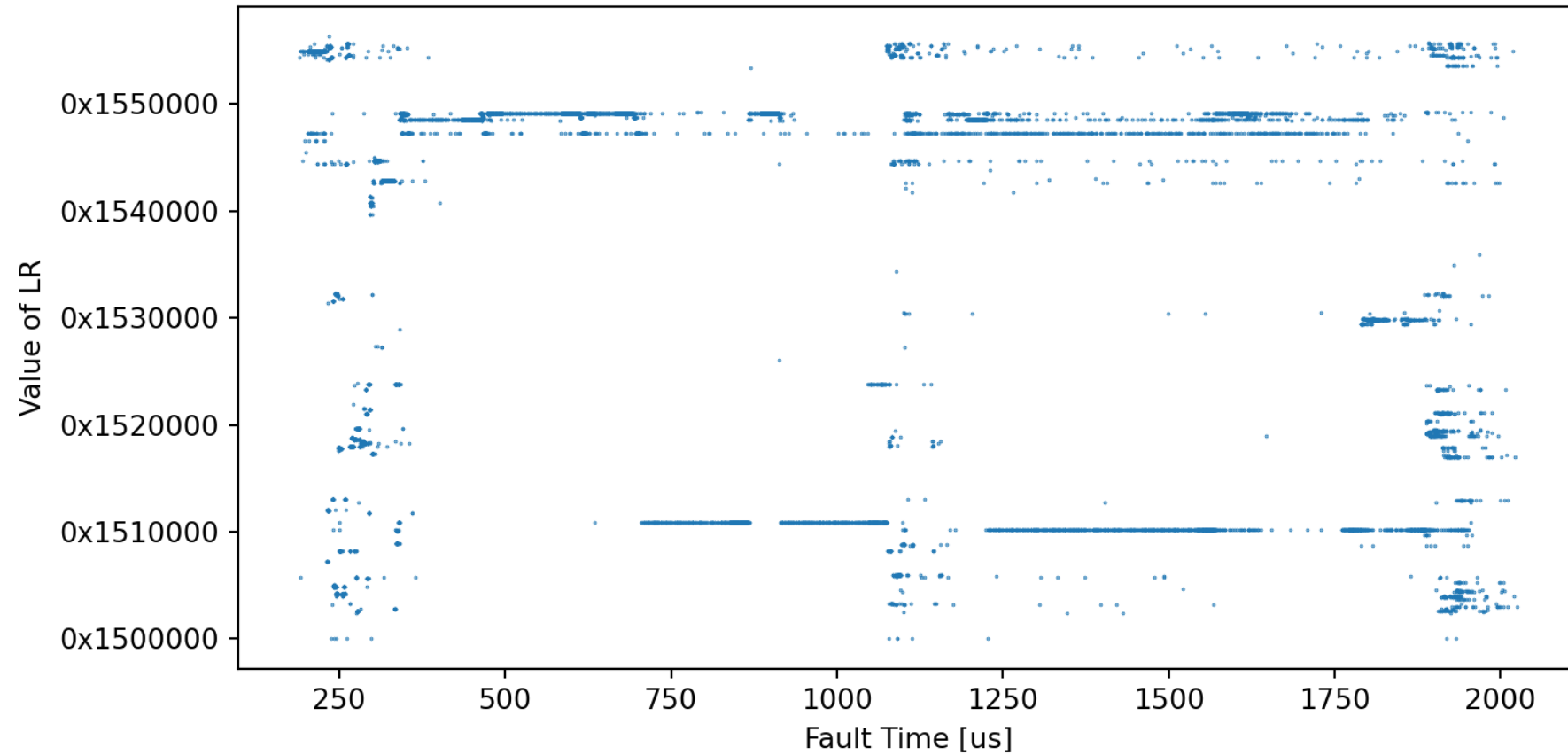
endr
    e_b _start // 4 bytes
endr
```

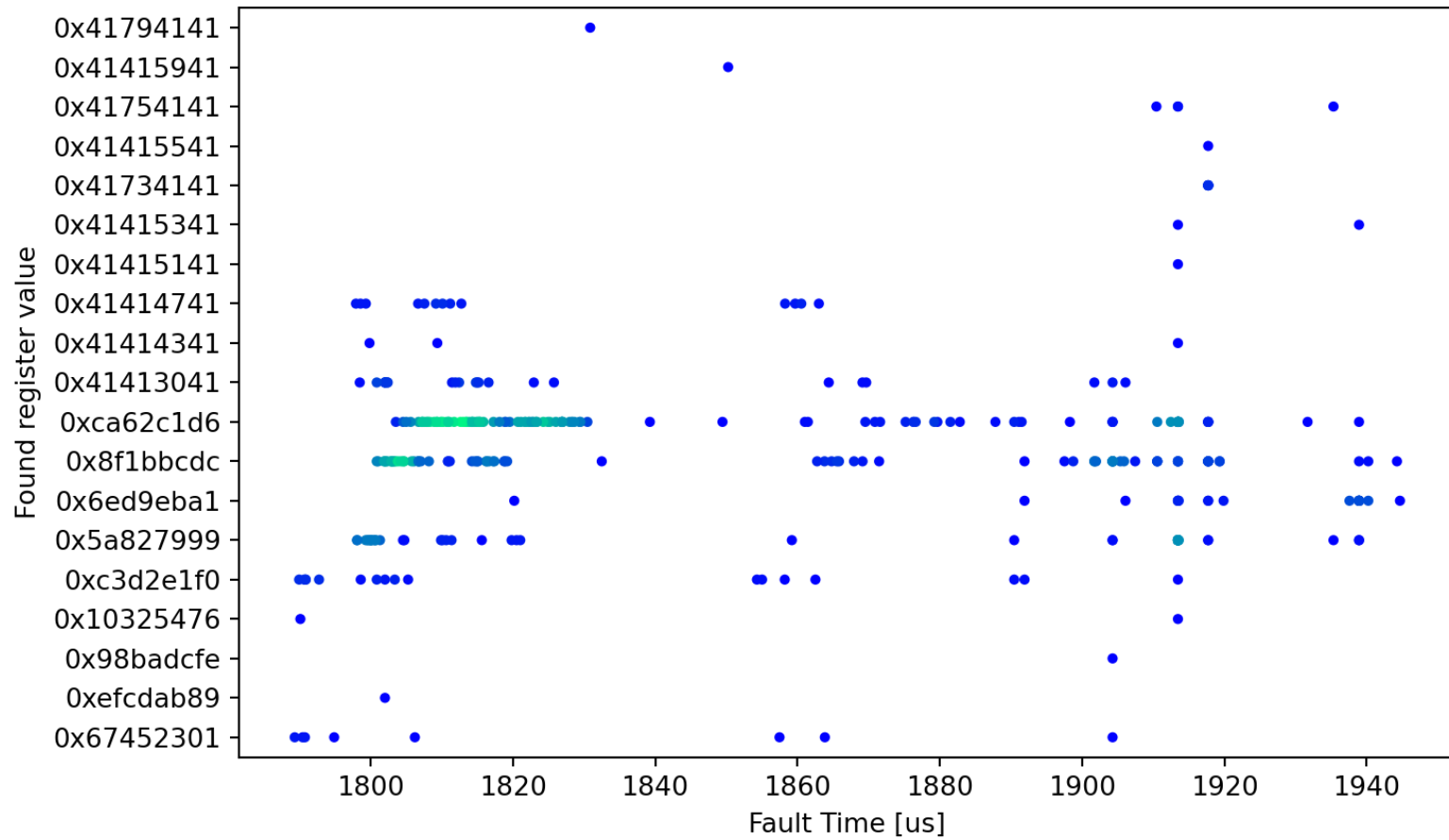
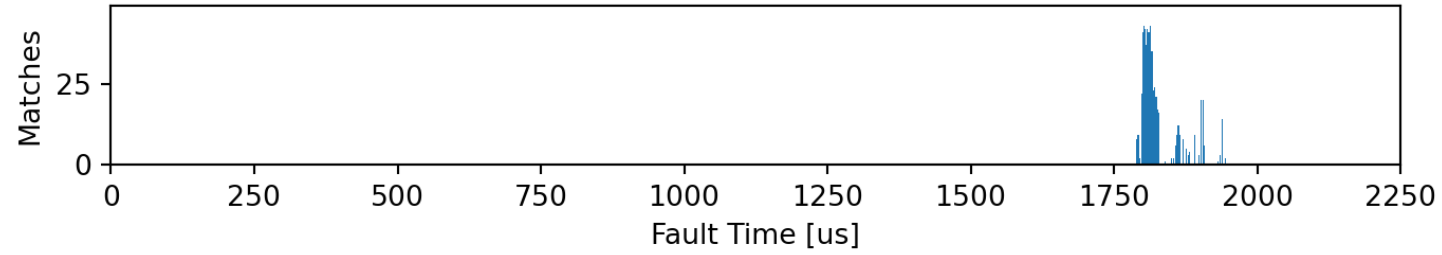


Search algorithm performance



Other interesting data leakage through faults

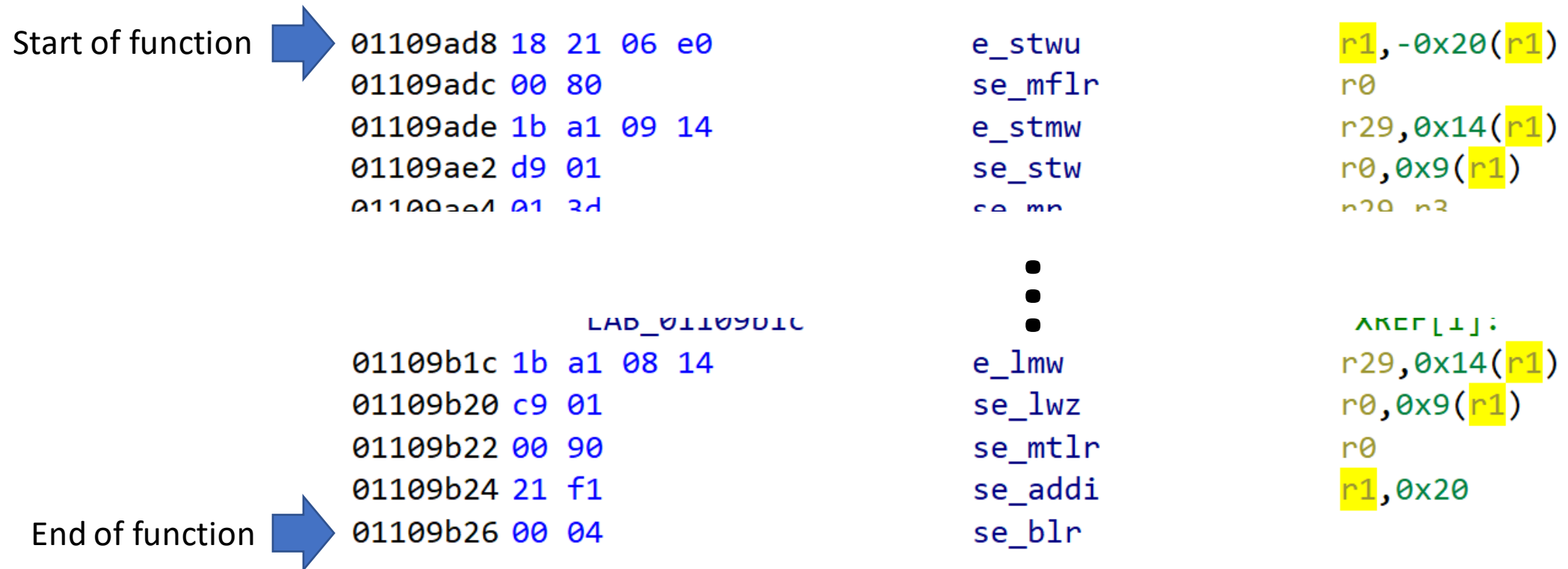




Program Counter corruption on PPC

- The PPC VLE instruction set is commonly found on many ECU which are critical for security.
- In PPC, 00 is an invalid instruction, and the CPU will immediately fault if zeroes are fetched as an instruction.
- Moreover, in PPC, the program counter and linker register are special registers, so they can't be written by normal MOV or LD instructions
- Is PPC immune to fault injection attacks?

Disruption of Instruction Flow: Misaligning the Stack Pointer

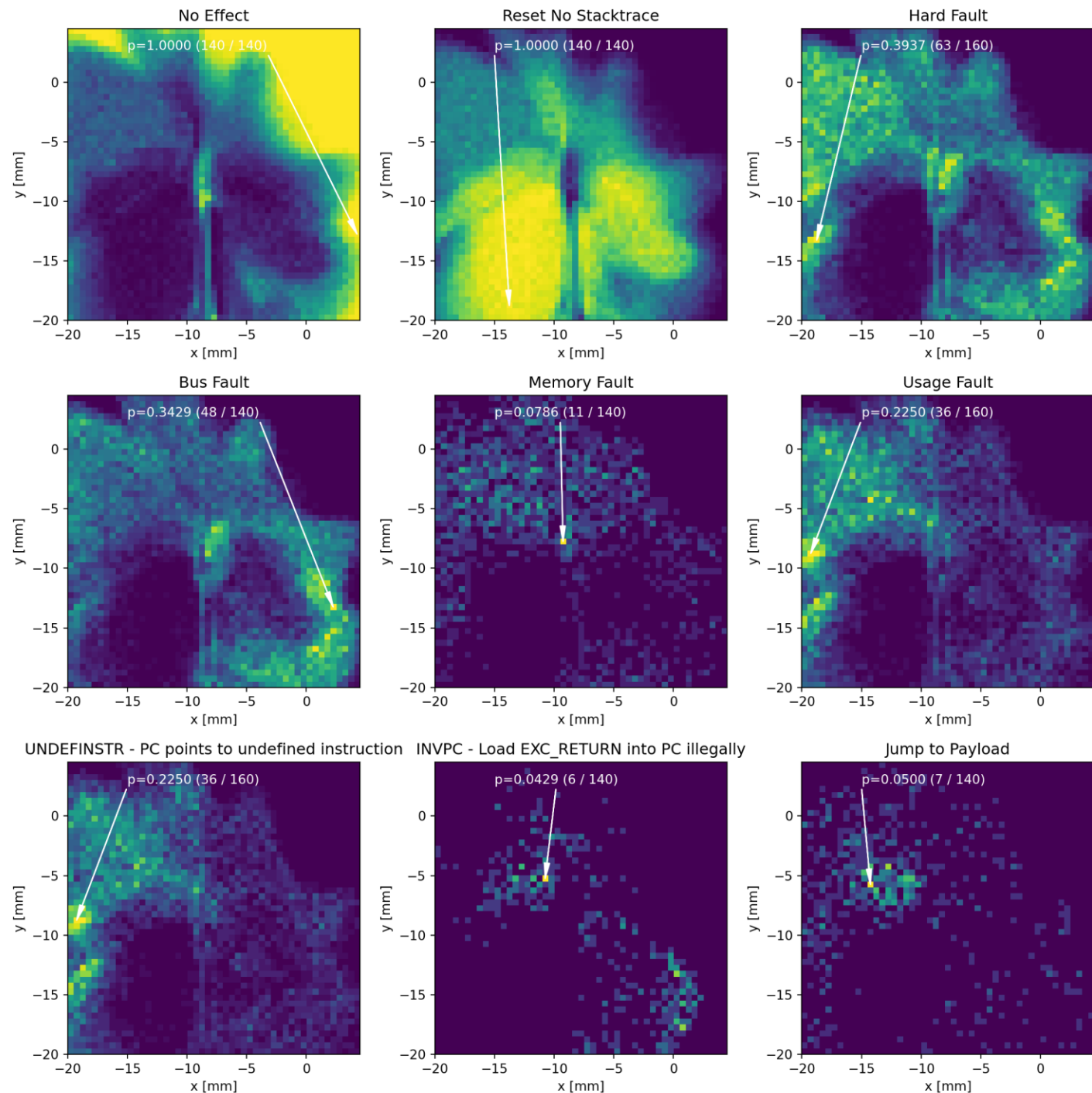


Exploitation

- Dumping memory
- JTAG
- Writing to Flash Memory
- Access to HSM API
- MPC / SPC Processors:
 - Manipulation of DCF Records (Chip Configuration)

How about ARM?

- Next generation of ECU Processors will be ARM
- Way-higher likelihood of PC corruption



Mitigation

- Use Memory Protection Units (MPU) => W^X
- Disable execution early in boot process to minimize attack surface
- Running the Bootloader in HSM might help:
 - Execution from functionally separated section of flash memory
 - Documentation for HSMs is kept secret, making exploit development harder
- ISO14229 (UDS) Software Update Process needs to be revised

Discussion

- UDS Protocol is broken in respect to fault injection
- We have Encrypted firmwares, that make the attack difficult
- It's a design flaw of UDS, adaptable to a wide range of ECUs
- No reverse engineering is required
- (Maybe HW-Reversing)
- Algorithms can be trained on EvalBoards and adapted to ECUs
- Attack can be automated
- PC corruption attack on PPC
- Attack was demonstrated on three different Gateway ECUs
- Different Processors, different OEMs, different Firmware, different Bootloader

Summary

- Efficient fault injection attacks demonstrated for code execution on real-world targets.
- EFISSA enables feasible black-box attacks
- Code injection into victim device's flash allows unauthorized execution via EMFI
- Higher success probability with larger programmable flash.
- Attack successful within minutes without knowledge of target software.
- Reproducible on multiple ECUs with minimal code changes.
- Cheap, available equipment; easy automation.
- Algorithm (EFISSA) reduces fault finding time from weeks to <1 hour.

Disclosure

- April 2022 major German OEMs were informed

Thank you for your patience!



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